CUNTZ-KRIEGER ALGEBRAS ASSOCIATED WITH HILBERT C*-QUAD MODULES OF COMMUTING MATRICES

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Abstract

Let $\mathcal{O}_{\mathcal{H}_{\kappa}^{A,B}}$ be the C^* -algebra associated with the Hilbert C^* -quad module arising from commuting matrices A, B with entries in $\{0, 1\}$. We will show that if the associated tiling space $X_{A,B}^{\kappa}$ is transitive, the C^* -algebra $\mathcal{O}_{\mathcal{H}_{\kappa}^{A,B}}$ is simple and purely infinite. In particular, for two positive integers N, M, the K-groups of the simple purely infinite C^* -algebra $\mathcal{O}_{\mathcal{H}_{\kappa}^{[N],[M]}}$ are computed by using the Euclidean algorithm.

1. Introduction

In [9], the author has introduced a notion of C^* -symbolic dynamical system, which is a generalization of a finite labeled graph, a λ -graph system and an automorphism of a unital C^* -algebra (cf. [10]). It is denoted by $(\mathcal{A}, \rho, \Sigma)$ and consists of a finite family $\{\rho_{\alpha}\}_{\alpha\in\Sigma}$ of endomorphisms of a unital C^* algebra \mathcal{A} such that $\rho_{\alpha}(Z_{\mathcal{A}}) \subset Z_{\mathcal{A}}, \alpha \in \Sigma$ and $\sum_{\alpha\in\Sigma} \rho_{\alpha}(1) \geq 1$ where $Z_{\mathcal{A}}$ denotes the center of \mathcal{A} , and endomorphisms are not necessarily unital. It provides a subshift Λ_{ρ} over Σ and a Hilbert C^* -bimodule $\mathcal{H}^{\rho}_{\mathcal{A}}$ over \mathcal{A} which gives rise to a C^* -algebra \mathcal{O}_{ρ} as a Cuntz-Pimsner algebra ([9], cf. [5], [16]). In [11] and [12], the author has extended the notion of C^* -symbolic dynamical system to C^* -textile dynamical system. The C^* -textile dynamical system $(\mathcal{A}, \rho, \eta, \Sigma^{\rho}, \Sigma^{\eta}, \kappa)$ consists of two C^* -symbolic dynamical systems $(\mathcal{A}, \rho, \Sigma^{\rho})$ and $(\mathcal{A}, \eta, \Sigma^{\eta})$ with a common unital C^* -algebra \mathcal{A} and a commutation relation between the endomorphisms ρ and η through a map κ stated below. Set

$$\Sigma^{\rho\eta} = \{ (\alpha, b) \in \Sigma^{\rho} \times \Sigma^{\eta} \mid \eta_b \circ \rho_{\alpha} \neq 0 \},$$

$$\Sigma^{\eta\rho} = \{ (a, \beta) \in \Sigma^{\eta} \times \Sigma^{\rho} \mid \rho_{\beta} \circ \eta_a \neq 0 \}.$$

We assume that there exists a bijection $\kappa : \Sigma^{\rho\eta} \to \Sigma^{\eta\rho}$, which we fix and call

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a specification. Then the required commutation relations are

(1.1)
$$\eta_b \circ \rho_\alpha = \rho_\beta \circ \eta_a$$
 if $\kappa(\alpha, b) = (a, \beta)$.

A C^* -textile dynamical system provides a two-dimensional subshift and a multi-structure of Hilbert C^* -bimodules that has multi-right actions and multi-left actions and multi-inner products. Such a multi-structure of Hilbert C^* -bimodules is called a Hilbert C^* -quad module, denoted by $\mathcal{H}_{\kappa}^{\rho,\eta}$. In [12], the author has introduced a C^* -algebra associated with the Hilbert C^* -quad module defined by a C^* -textile dynamical system. The C^* -algebra $\mathcal{O}_{\mathcal{H}_{\kappa}^{\rho,\eta}}$ has been constructed in a concrete way from the structure of the Hilbert C^* -quad module $\mathcal{H}_{\kappa}^{\rho,\eta}$ by a two-dimensional analogue of Pimsner's construction of C^* -algebras from Hilbert C^* -bimodules. It is generated by the quotient images of the creation operators on two-dimensional analogue of Fock Hilbert module by module maps of compact operators. As a result, the C^* -algebra has been proved to have a universal property subject to certain operator relations of generators encoded by structure of the Hilbert C^* -quad module of C^* -textile dynamical system ([12], cf. [13]).

Let *A*, *B* be two $N \times N$ matrices with entries in nonnegative integers. We assume that both *A* and *B* are essential, which means that they have no rows or columns identically to zero vector. They yield directed graphs $G_A = (V, E_A)$ and $G_B = (V, E_B)$ with a common vertex set $V = \{v_1, \ldots, v_N\}$ and edge sets E_A and E_B respectively, where the edge set E_A consists of A(i, j)-edges from the vertex v_i to the vertex v_j and E_B consists of B(i, j)-edges from the vertex v_i to the vertex v_j . Denote by s(e), r(e) the source vertex and the range vertex of an edge *e*. We set $\mathcal{A}_N = \mathbb{C}^N$. Denote by E_1, \ldots, E_N the set of minimal projections of \mathcal{A}_N defined by the standard basis of \mathbb{C}^N which correspond to the vertex set v_1, \ldots, v_N respectively, so that $\sum_{i=1}^N E_i = 1$. For $\alpha \in E_A$, define ρ_{α}^A an endomorphism of \mathcal{A}_N by $\rho_{\alpha}^A(E_i) = E_j$ if $s(\alpha) = v_i, r(\alpha) = v_j$, otherwise $\rho_{\alpha}^A(E_i) = 0$. Similarly we have an endomorphism ρ_a^B of \mathcal{A}_N for $a \in E_B$. We then have two C^* -symbolic dynamical systems $(\mathcal{A}_N, \rho^A, E_A)$ and $(\mathcal{A}_N, \rho^B, E_B)$ with $\mathcal{A}_N = \mathbb{C}^N$. Put

$$\Sigma^{AB} = \{ (\alpha, b) \in E_A \times E_B \mid r(\alpha) = s(b) \},\$$

$$\Sigma^{BA} = \{ (a, \beta) \in E_B \times E_A \mid r(a) = s(\beta) \}.$$

Assume that the commutation relation

$$(1.2) AB = BA$$

holds. We may take a bijection $\kappa : \Sigma^{AB} \to \Sigma^{BA}$ such that $s(\alpha) = s(a), r(b) = r(\beta)$ for $\kappa(\alpha, b) = (a, \beta)$, which we fix and call a specification by following

Nasu's terminology in [14]. This situation is called an LR-textile system introduced by Nasu ([14]). We then have a C^* -textile dynamical system (see [12])

$$(\mathscr{A}_N, \rho^A, \rho^B, E_A, E_B, \kappa).$$

Let us denote by $\mathscr{H}^{A,B}_{\kappa}$ the associated Hilbert *C*^{*}-quad module defined in [12]. We set

(1.3)
$$E_{\kappa} = \{ (\alpha, b, a, \beta) \in E_A \times E_B \times E_B \times E_A \mid \kappa(\alpha, b) = (a, \beta) \}.$$

Each element of E_{κ} is called a tile. Let $X_{A,B}^{\kappa} \subset (E_{\kappa})^{\mathbb{Z}^2}$ be the two-dimensional subshift of the Wang tilings of E_{κ} (cf. [19]). It consists of the two-dimensional configurations $x : \mathbb{Z}^2 \to E_{\kappa}$ compatible to their boundary edges on each tile, and is called the subshift of the tiling space for the specification $\kappa : \Sigma^{AB} \to \Sigma^{BA}$. We say that $X_{A,B}^{\kappa}$ is transitive if for two tiles $\omega, \omega' \in E_{\kappa}$, there exists $(\omega_{i,j})_{(i,j)\in\mathbb{Z}^2} \in X_{A,B}^{\kappa}$ such that $\omega_{0,0} = \omega, \omega_{i,j} = \omega'$ for some $(i, j) \in \mathbb{Z}^2$ with j < 0 < i. We set

(1.4)
$$\Omega_{\kappa} = \{(\alpha, a) \in E_A \times E_B \mid s(\alpha) = s(a), \\ \kappa(\alpha, b) = (a, \beta) \text{ for some } \beta \in E_A, b \in E_B\}$$

and define two $|\Omega_{\kappa}| \times |\Omega_{\kappa}|$ -matrices A_{κ} and B_{κ} with entries in $\{0, 1\}$ by

(1.5)
$$A_{\kappa}((\alpha, a), (\delta, b)) = \begin{cases} 1 & \kappa(\alpha, b) = (a, \beta) \text{ for some } \beta \in E_A, \\ 0 & \text{otherwise} \end{cases}$$

for $(\alpha, a), (\delta, b) \in \Omega_{\kappa}$,

(1.6)
$$B_{\kappa}((\alpha, a), (\beta, d)) = \begin{cases} 1 & \kappa(\alpha, b) = (a, \beta) \text{ for some } b \in E_B, \\ 0 & \text{otherwise} \end{cases}$$

for $(\alpha, a), (\beta, d) \in \Omega_{\kappa}$ respectively. Put the block matrix

(1.7)
$$H_{\kappa} = \begin{bmatrix} A_{\kappa} & A_{\kappa} \\ B_{\kappa} & B_{\kappa} \end{bmatrix}.$$

It has been proved in [12] that the C^* -algebra $\mathcal{O}_{\mathcal{H}^{A,B}_{\kappa}}$ associated with the Hilbert C^* -quad module $\mathcal{H}^{A,B}_{\kappa}$ is isomorphic to the Cuntz-Krieger algebra $\mathcal{O}_{H_{\kappa}}$ for the matrix H_{κ} (cf. [2]). In this paper, we first show the following theorem.

THEOREM 1.1 (Theorem 2.10). The subshift $X_{A,B}^{\kappa}$ of the tiling space is transitive if and only if the matrix H_{κ} is irreducible. In this case, H_{κ} satisfies condition (I) in the sense of [2]. Hence if the subshift $X_{A,B}^{\kappa}$ of the tiling space is transitive, the C^{*}-algebra $\mathcal{O}_{\mathcal{H}^{A,B}}$ is simple and purely infinite.

We then see the following theorem.

THEOREM 1.2 (Theorem 2.11). If the matrix A or B is irreducible, the matrix H_{κ} is irreducible and satisfies condition (I), so that the C^{*}-algebra $\mathcal{O}_{\mathcal{H}^{A,B}}$ is simple and purely infinite.

Let *N*, *M* be positive integers with *N*, *M* > 1. They give 1×1 commuting matrices A = [N], B = [M]. The directed graph G_A associated to the matrix A = [N] is a graph consists of *N*-self directed loops denoted by E_A with a vertex denoted by *v*. Similarly the directed graph G_B consists of *M*-self directed loops denoted by E_B with the vertex *v*. We fix a specification $\kappa : E_A \times E_B \rightarrow E_B \times E_A$ defined by exchanging $\kappa(\alpha, a) = (a, \alpha)$ for $(\alpha, a) \in E_A \times E_B$. The specification is called the exchanging specification between E_A and E_B . We present the following K-theory formulae for the C^* -algebra $\mathcal{O}_{\mathcal{H}_{\kappa}^{[N],[M]}}$. In its computation, the Euclidean algorithm is used. For integers $1 < N \leq M \in \mathbb{N}$, let d = (N - 1, M - 1) be the greatest common divisor of N - 1 and M - 1. Let $k_0, k_1, \ldots, k_{j+1}$ be the successive integral quotients of M - 1 by N - 1 by the Euclidean algorithm such as

$$M - 1 = (N - 1)k_0 + r_0 \quad \text{for some} \quad k_0 \in Z_+, \quad 0 < r_0 < N - 1,$$

$$N - 1 = r_0k_1 + r_1 \quad \text{for some} \quad k_1 \in Z_+, \quad 0 < r_1 < r_0,$$

$$\vdots \quad r_{j-2} = r_{j-1}k_j + r_j \quad \text{for some} \quad k_j \in Z_+, \quad 0 < r_j < r_{j-1},$$

$$r_{j-1} = dk_{j+1}.$$

THEOREM 1.3 (Theorem 3.5). For integers $1 < N \leq M \in \mathbb{N}$ and the exchanging specification κ between directed N-loops and M-loops, the C*-algebra $\mathcal{O}_{\mathcal{H}_{\kappa}^{[N],[M]}}$ is a simple purely infinite Cuntz-Krieger algebra whose K-groups are

$$K_{1}(\mathcal{O}_{\mathscr{H}_{\kappa}^{[N],[M]}}) \cong 0,$$

$$K_{0}(\mathcal{O}_{\mathscr{H}_{\kappa}^{[N],[M]}}) \cong \overbrace{\mathsf{Z}/(N-1)\mathsf{Z} \oplus \cdots \oplus \mathsf{Z}/(N-1)\mathsf{Z}}^{M-2} \oplus \overbrace{\mathsf{Z}/(M-1)\mathsf{Z} \oplus \cdots \oplus \mathsf{Z}/(M-1)\mathsf{Z}}^{N-2} \oplus \overbrace{\mathsf{Z}/(M-1)\mathsf{Z} \oplus \cdots \oplus \mathsf{Z}/(M-1)\mathsf{Z}}^{N-2} \oplus [\mathsf{Z}/d\mathsf{Z} \oplus \mathsf{Z}/[k_{1}, k_{2}, \dots, k_{j+1}](M-1)(M+N-1)\mathsf{Z}}$$

where d = (N - 1, M - 1) the greatest common divisor of N - 1 and M - 1, and the sequence $k_0, k_1, \ldots, k_{j+1}$ is the successive integral quotients of M - 1by N - 1 by the Euclidean algorithm above, and the integer $[k_1, k_2, \ldots, k_{j+1}]$ is defined by inductively

$$[k_0] = 1, \quad [k_1] = k_1, \quad [k_1, k_2] = 1 + k_1 k_2, \\ \dots, \quad [k_1, k_2, \dots, k_{j+1}] = [k_1, k_2, \dots, k_j] k_{j+1} + [k_1, \dots, k_{j-1}].$$

We remark that the C^* -algebras studied in this paper are different from the higher rank graph algebras studied by G. Robertson-T. Steger [18], A. Kumjian-D. Pask [6], V. Deaconu [3], etc., (cf. [4], [17], [15], etc.). Throughout the paper, we denote by N and by Z_+ the set of positive integers and the set of nonnegative integers respectively.

2. Transitivity of tilings $X_{A,B}^{\kappa}$ and simplicity of $\mathcal{O}_{\mathcal{H}_{\ell}^{A,B}}$

Let Σ be a finite set. The two-dimensional full shift over Σ is defined to be

$$\Sigma^{Z^{2}} = \{ (x_{i,j})_{(i,j) \in \mathbb{Z}^{2}} \mid x_{i,j} \in \Sigma \}.$$

An element $x \in \Sigma^{Z^2}$ is regarded as a function $x : Z^2 \to \Sigma$ which is called a configuration on Z^2 . For a vector $m = (m_1, m_2) \in Z^2$, let $\sigma^m : \Sigma^{Z^2} \to \Sigma^{Z^2}$ be the translation along vector *m* defined by

$$\sigma^m((x_{i,j})_{(i,j)\in \mathbb{Z}^2}) = (x_{i+m_1,j+m_2})_{(i,j)\in \mathbb{Z}^2}.$$

A subset $X \subset \Sigma^{Z^2}$ is said to be translation invariant if $\sigma^m(X) = X$ for all $m \in Z^2$. It is obvious to see that a subset $X \subset \Sigma^{Z^2}$ is translation invariant if and only if X is invariant only both horizontally and vertically, that is, $\sigma^{(1,0)}(X) = X$ and $\sigma^{(0,1)}(X) = X$. For $k \in Z_+$, put

$$[-k,k]^{2} = \{(i,j) \in \mathsf{Z}^{2} \mid -k \le i, j \le k\} = [-k,k] \times [-k,k].$$

A metric *d* on Σ^{Z^2} is defined by for $x, y \in \Sigma^{Z^2}$ with $x \neq y$

$$d(x, y) = \frac{1}{2^k}$$
 if $x_{(0,0)} = y_{(0,0)}$,

where $k = \max\{k \in Z_+ | x_{[-k,k]^2} = y_{[-k,k]^2}\}$. If $x_{(0,0)} \neq y_{(0,0)}$, put k = -1 on the above definition. If x = y, we set d(x, y) = 0. A two-dimensional subshift X is defined to be a closed, translation invariant subset of Σ^{Z^2} (cf. [8, p. 467]). A two-dimensional subshift X is said to have the *diagonal property* if for $(x_{i,j})_{(i,j)\in Z^2}, (y_{i,j})_{(i,j)\in Z^2} \in X$, the conditions $x_{i,j} = y_{i,j}, x_{i+1,j-1} = y_{i+1,j-1}$ imply $x_{i,j-1} = y_{i,j-1}, x_{i+1,j} = y_{i+1,j}$ (see [11]). The diagonal property has the following property: for $x \in X$ and $(i, j) \in Z^2$, the configuration x is determined by the diagonal line $(x_{i+n,j-n})_{n\in Z}$ through (i, j). We henceforth go back to our previous situation of C^* -textile dynamical system $(\mathscr{A}_N, \rho^A, \rho^B, E_A, E_B, \kappa)$ coming from $N \times N$ commuting matrices A and B with specification κ as in Section 1. We always assume that both matrices A and B are essential. Recall that the matrices A and B give rise to directed graphs $G_A = (V, E_A)$ and $G_B = (V, E_B)$ with a common vertex set $V = \{v_1, \ldots, v_N\}$ and edge sets E_A and E_B respectively, where the edge set E_A consists of A(i, j)-edges from the vertex v_i to the vertex v_j and E_B consists of B(i, j)-edges from the vertex v_i to the vertex v_j . A two-dimensional subshift $X_{A,B}^{\kappa}$ is defined as in the following way. Let Σ be the set E_{κ} of tiles defined in (1.3). For $\omega = (\alpha, b, a, \beta) \in E_{\kappa}$, define maps $t(= \text{top}), b(= \text{bottom}) : E_{\kappa} \to E_A$ and $l(= \text{left}), r(= \text{right}) : E_{\kappa} \to E_B$ by setting

$$t(\omega) = \alpha, \quad b(\omega) = \beta, \quad l(\omega) = a, \quad r(\omega) = b$$

as in the following figure:

$$\begin{array}{c} \circ & \xrightarrow{a=l(\omega)} \circ \\ a=l(\omega) \downarrow & \qquad \qquad \downarrow b=r(\omega) \\ \circ & \xrightarrow{\beta=b(\omega)} \circ \end{array}$$

A configuration $(\omega_{i,j})_{(i,j)\in\mathbb{Z}^2} \in E_{\kappa}^{\mathbb{Z}^2}$ is said to be *paved* if the conditions

$$t(\omega_{i,j}) = b(\omega_{i,j+1}), \qquad r(\omega_{i,j}) = l(\omega_{i+1,j}),$$

$$l(\omega_{i,j}) = r(\omega_{i-1,j}), \qquad b(\omega_{i,j}) = t(\omega_{i,j-1})$$

hold for all $(i, j) \in \mathbb{Z}^2$. Let $X_{A,B}^{\kappa}$ be the set of all paved configurations $(\omega_{i,j})_{(i,j)\in\mathbb{Z}^2} \in E_{\kappa}^{\mathbb{Z}^2}$. It consists of the Wang tilings of the tiles of E_{κ} (see [19]). The following proposition is easy.

PROPOSITION 2.1. $X_{A,B}^{\kappa}$ is a two-dimensional subshift having the diagonal property.

We write $\mathscr{A}_N = \mathsf{C} E_1 \oplus \cdots \oplus \mathsf{C} E_N$ for the minimal projections $E_i, i = 1, \ldots, N$ of \mathscr{A}_N such that $\sum_{i=1}^N E_i = 1$. Let us define the matrices \widehat{A}, \widehat{B} by setting for $\alpha \in E_A, a \in E_B, i, j = 1, \ldots, N$,

$$\widehat{A}(i, \alpha, j) = \begin{cases} 1 & \text{if } s(\alpha) = i, r(\alpha) = j, \\ 0 & \text{otherwise,} \end{cases}$$
$$\widehat{B}(i, a, j) = \begin{cases} 1 & \text{if } s(a) = i, r(a) = j, \\ 0 & \text{otherwise.} \end{cases}$$

Recall that the endomorphisms ρ_{α}^{A} , ρ_{a}^{B} of \mathscr{A}_{N} for $\alpha \in E_{A}$, $a \in E_{B}$ are defined

by

$$\rho_{\alpha}^{A}(E_{i}) = \sum_{j=1}^{N} \widehat{A}(i,\alpha,j)E_{j}, \qquad \rho_{a}^{B}(E_{i}) = \sum_{j=1}^{N} \widehat{B}(i,a,j)E_{j}$$

for i = 1, ..., N. They yield the C^* -textile dynamical system

$$(\mathscr{A}_N, \rho^A, \rho^B, E_A, E_B, \kappa)$$

with specification κ ([12]). Let $e_{\omega}, \omega \in E_{\kappa}$ be the standard basis of $C^{|E_{\kappa}|}$. Put the projection $E_{\omega} = \rho_b^B \circ \rho_{\alpha}^A(1) (= \rho_{\beta}^A \circ \rho_a^B(1)) \in \mathscr{A}_N$ for $\omega = (\alpha, b, a, \beta) \in E_{\kappa}$. We set

$$\mathscr{H}^{A,B}_{\kappa} = \sum_{\omega \in E_{\kappa}} e_{\omega} \otimes E_{\omega} \mathscr{A}_{N}.$$

Then $\mathscr{H}^{A,B}_{\kappa}$ has a natural structure of not only Hilbert *C**-right module over \mathscr{A}_{N} but also two other Hilbert *C**-bimodule structure, called Hilbert *C**-quad module. By two-dimensional analogue of Pimsner's construction of Hilbert *C**-bimodule algebra ([16]), we have introduced a *C**-algebra $\mathscr{O}_{\mathscr{H}^{A,B}_{\kappa}}$ (see [12] and [13] for detail construction). Let Ω_{κ} be the subset of $E_A \times E_B$ defined in (1.4). We define two $|\Omega_{\kappa}| \times |\Omega_{\kappa}|$ -matrcies A_{κ} and B_{κ} with entries in {0, 1} as in (1.5) and (1.6). The matrices A_{κ} and B_{κ} represent the concatenations of edges as in the following figures respectively:

and

Let H_{κ} be the $2|\Omega_{\kappa}| \times 2|\Omega_{\kappa}|$ matrix defined in (1.7). We have proved the following result in [12].

THEOREM 2.2. The C*-algebra $\mathcal{O}_{\mathcal{H}^{A,B}_{\kappa}}$ associated with Hilbert C*-quad module $\mathcal{H}^{A,B}_{\kappa}$ defined by commuting matrices A, B and a specification κ is isomorphic to the Cuntz-Krieger algebra $\mathcal{O}_{H_{\kappa}}$ for the matrix H_{κ} . Its K-groups $K_*(\mathcal{O}_{H_{\kappa}})$ are computed as

$$K_0(\mathcal{O}_{H_{\kappa}}) = \mathsf{Z}^n / (A_{\kappa} + B_{\kappa} - I_n) \mathsf{Z}^n, \quad K_1(\mathcal{O}_{H_{\kappa}}) = \operatorname{Ker}(A_{\kappa} + B_{\kappa} - I_n) \text{ in } \mathsf{Z}^n,$$

where $n = |\Omega_{\kappa}|.$

We will study a relationship between transitivity of the tiling space $X_{A,B}^{\kappa}$ and simplicity of the C^* -algebra $\mathcal{O}_{\mathcal{H}_{\kappa}^{A,B}}$. An essential matrix with entries in {0, 1} is said to satisfy condition (I) (in the sense of [2]) if the shift space defined by the topological Markov chain for the matrix is homeomorphic to a Cantor discontinuum. The condition is equivalent to the condition that every loop in the associated directed graph has an exit ([7]). It is a fundamental result that a Cuntz-Krieger algebra is simple and purely infinite if the underlying matrix is irreducible and satisfies condition (I) ([2]). We will find a condition of the two-dimensional subshift $X_{A,B}^{\kappa}$ of the tiling space under which the matrix H_{κ} is irreducible and satisfies condition (I). Hence the condition on $X_{A,B}^{\kappa}$ yields the simplicity and purely infiniteness of the algebra $\mathcal{O}_{\mathcal{H}^{A,B}}$.

We are assuming that both of the matrices A and B are essential. Then we have

LEMMA 2.3. Both of the matrices A_{κ} and B_{κ} are essential.

PROOF. For $(\alpha, a) \in \Omega_{\kappa}$, by definition of Ω_{κ} , there exist $\beta \in E_A$ and $b \in E_B$ such that $\kappa(\alpha, b) = (a, \beta)$. Since *A* is essential, one may take $\beta_1 \in E_A$ such that $s(\beta_1) = r(b)(=r(\beta))$. Hence $(b, \beta_1) \in \Sigma^{BA}$. Put $(\alpha_1, b_1) = \kappa^{-1}(b, \beta_1) \in \Sigma^{AB}$ so that $(\alpha_1, b) \in \Omega_{\kappa}$ and $A_{\kappa}((\alpha, a), (\alpha_1, b)) = 1$ as in the following figure:

$$\begin{array}{c} \circ & \stackrel{\frown}{\longrightarrow} & \circ & \stackrel{\frown}{\longrightarrow} & \circ \\ a \downarrow & & b \downarrow & & b_1 \downarrow \\ \circ & \stackrel{\beta}{\longrightarrow} & \circ & \stackrel{\beta_1}{\longrightarrow} \end{array}$$

For $(\delta, b) \in \Omega_{\kappa}$ there exists $\alpha \in E_A$ such that $r(\alpha) = s(\delta)(=s(b))$ because *A* is essential. Hence $(\alpha, b) \in \Sigma^{AB}$. Put $(a, \beta) = \kappa(\alpha, b)$ so that $(\alpha, a) \in \Omega_{\kappa}$ and $A_{\kappa}((\alpha, a), (\delta, b)) = 1$ as in the following figure:

$$\begin{array}{ccc} \circ & \xrightarrow{\alpha} & \circ & \xrightarrow{\delta} \circ \\ a \downarrow & & b \downarrow \\ \circ & \xrightarrow{\beta} & \circ \end{array}$$

Therefore one sees that A_{κ} is essential, and similarly that B_{κ} is essential.

Hence we have

PROPOSITION 2.4. The matrix H_{κ} is essential and satisfies condition (I).

PROOF. By the previous lemma, both of the matrices A_{κ} and B_{κ} are essential. Hence every row of A_{κ} and of B_{κ} has at least one 1. Since

$$H_{\kappa} = \begin{bmatrix} A_{\kappa} & A_{\kappa} \\ B_{\kappa} & B_{\kappa} \end{bmatrix},$$

every row of H_{κ} has at least two 1's. This implies that a loop in the directed graph associated to H_{κ} must has an exit so that H_{κ} satisfies condition (I).

For
$$(\alpha, a), (\alpha', a') \in \Omega_{\kappa}$$
, and $C, D = A$ or B , we have

$$[C_{\kappa}D_{\kappa}]((\alpha, a), (\alpha', a')) = \sum_{(\alpha_1, a_1) \in \Omega_{\kappa}} C_{\kappa}((\alpha, a), (\alpha_1, a_1)) D_{\kappa}((\alpha_1, a_1), (\alpha', a')).$$

Hence $[A_{\kappa}A_{\kappa}]((\alpha, a), (\alpha', a')) \neq 0$ if and only if there exists $(\alpha_1, a_1) \in \Omega_{\kappa}$ such that $\kappa(\alpha, a_1) = (a, \beta)$ for some $\beta \in E_A$ and $\kappa(\alpha_1, a') = (a_1, \beta_1)$ for some $\beta_1 \in E_A$ as in the following figure:



And also $[A_{\kappa}B_{\kappa}]((\alpha, a), (\alpha', a')) \neq 0$ if and only if there exists $(\alpha_1, a_1) \in \Omega_{\kappa}$ such that $\kappa(\alpha, a_1) = (a, \beta)$ for some $\beta \in E_A$ and $\kappa(\alpha_1, b_1) = (a_1, \alpha')$ for some $b_1 \in E_B$ as in the following figure:



Similarly $[B_{\kappa}A_{\kappa}]((\alpha, a), (\alpha', a')) \neq 0$ if and only if there exists $(\alpha_1, a_1) \in \Omega_{\kappa}$ such that $\kappa(\alpha, b) = (a, \alpha_1)$ for some $b \in E_B$ and $\kappa(\alpha_1, a') = (a_1, \beta_1)$ for some $\beta_1 \in E_A$ as in the following figure:



And also $[B_{\kappa}B_{\kappa}]((\alpha, a), (\alpha', a')) \neq 0$ if and only if there exists $(\alpha_1, a_1) \in \Omega_{\kappa}$ such that $\kappa(\alpha, b) = (a, \alpha_1)$ for some $b \in E_B$ and $\kappa(\alpha_1, b_1) = (a_1, \alpha')$ for some $b_1 \in E_B$ as in the following figure:

$$\begin{array}{c} \circ & \xrightarrow{\alpha} & \circ \\ a \downarrow & & b \downarrow \\ \circ & \xrightarrow{\alpha_1} & \circ \\ a_1 \downarrow & & b_1 \downarrow \\ \circ & \xrightarrow{\alpha'} & \circ \\ a_1 \downarrow & & \end{array}$$

LEMMA 2.5. $A_{\kappa}B_{\kappa} = B_{\kappa}A_{\kappa}$.

PROOF. For $(\alpha, a), (\alpha', a') \in \Omega_{\kappa}$, we have $[A_{\kappa}B_{\kappa}]((\alpha, a), (\alpha', a')) = m$ if and only if there exist $(\alpha_i, a'_i) \in \Omega_{\kappa}, i = 1, ..., m$ such that $\kappa(\alpha, a'_i) = (a, \beta_i)$ for some $\beta_i \in E_A$ and $\kappa(\alpha_i, b_i) = (a'_i, \alpha')$ for some $b_i \in E_B$ as in the following figure:

$$\begin{array}{c} \circ & \xrightarrow{\alpha} & \circ & \xrightarrow{\alpha_i} & \circ \\ a \downarrow & a_i' \downarrow & b_i \downarrow \\ \circ & \xrightarrow{\beta_i} & \circ & \xrightarrow{\alpha'} & \circ \\ & & a' \downarrow \end{array}$$

Put $(a_i, \beta'_i) = \kappa(\beta_i, a')$. We then have $(\beta_i, a_i) \in \Omega_{\kappa}$ as in the following figure:

$$\begin{array}{ccc} \circ & \xrightarrow{\alpha} & \circ \\ a \downarrow & a'_i \downarrow \\ \circ & \xrightarrow{\beta_i} & \circ & \xrightarrow{\alpha'} \\ a_i \downarrow & a'_i \downarrow \\ \circ & \xrightarrow{\beta'_i} & \circ \end{array}$$

If $(\beta_i, a_i) = (\beta_j, a_j)$ in Ω_{κ} , then we have $\beta_i = \beta_j$ so that $a'_i = a'_j$ and hence $\alpha_i = \alpha_j$. Therefore we have $[B_{\kappa}A_{\kappa}]((\alpha, a), (\alpha', a')) = m$.

LEMMA 2.6. The following four conditions are equivalent.

- (i) The matrix H_{κ} is irreducible.
- (ii) For $(\alpha, a), (\alpha', a') \in \Omega_{\kappa}$, there exist $n, m \in Z_+$ such that

$$A_{\kappa}(A_{\kappa} + B_{\kappa})^{n}((\alpha, a), (\alpha', a')) > 0,$$

$$B_{\kappa}(A_{\kappa} + B_{\kappa})^{m}((\alpha, a), (\alpha', a')) > 0.$$

- (iii) The matrix $A_{\kappa} + B_{\kappa}$ is irreducible.
- (iv) For $(\alpha, a), (\alpha', a') \in \Omega_{\kappa}$, there exists a paved configuration $(\omega_{i,j})_{(i,j)\in\mathbb{Z}^2} \in X_{A,B}^{\kappa}$ such that

$$t(\omega_{0,0}) = \alpha$$
, $l(\omega_{0,0}) = a$, $t(\omega_{i,j}) = \alpha'$, $l(\omega_{i,j}) = a'$

for some $(i, j) \in Z^2$ with j < 0 < i.

PROOF. (i) \Leftrightarrow (ii): The identity

(2.1)
$$H_{\kappa}^{n} = \begin{bmatrix} A_{\kappa}(A_{\kappa} + B_{\kappa})^{n} & A_{\kappa}(A_{\kappa} + B_{\kappa})^{n} \\ B_{\kappa}(A_{\kappa} + B_{\kappa})^{n} & B_{\kappa}(A_{\kappa} + B_{\kappa})^{n} \end{bmatrix}$$

implies the equivalence between (i) and (ii).

(ii) \Rightarrow (iii): Suppose that for (α, a) , $(\alpha', a') \in \Omega_{\kappa}$, there exists $n \in Z_+$ such that $A_{\kappa}(A_{\kappa} + B_{\kappa})^n((\alpha, a), (\alpha', a')) > 0$ so that

$$(A_{\kappa}+B_{\kappa})^{n+1}((\alpha,a),(\alpha',a'))>0.$$

Hence the matrix $A_{\kappa} + B_{\kappa}$ is irreducible.

(iii) \Rightarrow (ii): As A_{κ} and B_{κ} are both essential, for $(\alpha, a), (\alpha', a') \in \Omega_{\kappa}$ there exists $(\alpha_1, \alpha_1), (\alpha_2, \alpha_2) \in \Omega_{\kappa}$ such that

$$A_{\kappa}((\alpha, a), (\alpha_1, a_1)) = 1,$$

 $B_{\kappa}((\alpha, a), (\alpha_2, a_2)) = 1.$

Since $A_{\kappa} + B_{\kappa}$ is irreducible, there exist $n, m \in Z_{+}$ such that

$$(A_{\kappa} + B_{\kappa})^{n}((\alpha_{1}, a_{1}), (\alpha', a')) > 0,$$

$$(A_{\kappa} + B_{\kappa})^{m}((\alpha_{2}, a_{2}), (\alpha', a')) > 0.$$

Hence we have

$$A_{\kappa}(A_{\kappa}+B_{\kappa})^{n}((\alpha,a),(\alpha',a')) > 0,$$

$$B_{\kappa}(A_{\kappa}+B_{\kappa})^{m}((\alpha,a),(\alpha',a')) > 0.$$

(ii) \Rightarrow (iv): For $(\alpha, a), (\alpha', a') \in \Omega_{\kappa}$, take $(\alpha_1, a_1) \in \Omega_{\kappa}$ and $\beta \in E_A$ such that $\kappa(\alpha, a_1) = (a, \beta)$. By (ii), there exists $m \in Z_+$ with $B_{\kappa}(A_{\kappa} + B_{\kappa})^m((\alpha, a), (\alpha', a')) > 0$. One may take $b' \in E_B$ and $\beta' \in E_A$ satisfying $\kappa(\alpha', b') = (a', \beta')$, so that there exists a paved configuration $(\omega_{i,j})_{(i,j)\in Z^2} \in X_{A,B}^{\kappa}$ such that $\omega_{0,0} = (\alpha, a_1, a, \beta)$ and $\omega_{i,j} = (\alpha', b', a', \beta')$ for some $(i, j) \in X_{A,B}$

 Z^2 with j < 0 < i as in the following figure:



 $(iv) \Rightarrow (ii)$: The assertion is clear.

DEFINITION 2.7. A two-dimensional subshift $X_{A,B}^{\kappa}$ is said to be *transitive* if for two tiles $\omega, \omega' \in E_{\kappa}$ there exists a paved configuration $(\omega_{i,j})_{(i,j)\in \mathbb{Z}^2} \in X_{A,B}^{\kappa}$ such that $\omega_{0,0} = \omega$ and $\omega_{i,j} = \omega'$ for some $(i, j) \in \mathbb{Z}^2$ with j < 0 < i.

THEOREM 2.8. The subshift $X_{A,B}^{\kappa}$ of the tiling space is transitive if and only if the matrix H_{κ} is irreducible.

PROOF. Assume that the matrix H_{κ} is irreducible. Hence the condition (iv) in Lemma 2.6 holds. Let $\omega = (\alpha, b, a, \beta)$, $\omega' = (\alpha', b', a', \beta') \in E_{\kappa}$ be two tiles. Since A is essential, there exists $\beta_1 \in E_A$ such that $r(\beta)(=r(b)) = s(\beta_1)$, so that $(b, \beta_1) \in \Sigma^{BA}$. One may take $(\alpha_1, b_1) \in \Sigma^{AB}$ such that $\kappa(\alpha_1, b_1) = (b, \beta_1)$ and hence $(\alpha_1, b) \in \Omega_{\kappa}$ as in the following figure:

$$\begin{array}{ccc} \circ & \xrightarrow{\alpha} & \circ & \xrightarrow{\alpha_1} & \circ \\ a & & b & & b_1 \\ \circ & \xrightarrow{\beta} & \circ & \xrightarrow{\beta_1} & \circ \end{array}$$

For $(\alpha_1, b), (\alpha', a') \in \Omega_{\kappa}$, by (iv) in Lemma 2.6, there exists $(\omega_{i,j})_{(i,j)\in\mathbb{Z}^2} \in X_{A,B}^{\kappa}$ such that $t(\omega_{0,0}) = \alpha_1, l(\omega_{0,0}) = b, t(\omega_{i,j}) = \alpha', l(\omega_{i,j}) = a'$ for some $(i, j) \in \mathbb{Z}^2$ with j < 0 < i. Since $X_{A,B}^{\kappa}$ has the diagonal property, there exists a paved configuration $(\omega'_{i,j})_{(i,j)\in\mathbb{Z}^2} \in X_{A,B}^{\kappa}$ such that $\omega'_{0,0} = \omega, \omega'_{i,j} = \omega'$. Hence $X_{A,B}^{\kappa}$ is transitive.

Conversely assume that $X_{A,B}^{\kappa}$ is transitive. For $(\alpha, a), (\alpha', a') \in \Omega_{\kappa}$, there exist $b, b' \in E_B$ and $\beta, \beta' \in E_A$ such that $\omega = (\alpha, b, a, \beta), \omega' = (\alpha', b', a', \beta') \in E_{\kappa}$. It is clear that the transitivity of $X_{A,B}^{\kappa}$ implies the condition (iv) in Lemma 2.6, so that H_{κ} is irreducible.

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LEMMA 2.9. If A or B is irreducible, $X_{A,B}^{\kappa}$ is transitive.

PROOF. Suppose that the matrix A is irreducible. For two tiles $\omega = (\alpha, b, a, \beta), \omega' = (\alpha', b', a', \beta') \in E_{\kappa}$, there exist concatenated edges $(\beta, \beta_1, \ldots, \beta_n, \alpha')$ in the graph G_A for some edges $\beta_1, \ldots, \beta_n \in E_A$. Since $X_{A,B}^{\kappa}$ has the diagonal property, there exists a configuration $(\omega_{i,j})_{(i,j)\in\mathbb{Z}^2} \in X_{A,B}^{\kappa}$ such that $\omega' = \omega_{i,j}$ for some i > 0, j = -1. Hence $X_{A,B}^{\kappa}$ is transitive.

Since the *C*^{*}-algebra $\mathcal{O}_{\mathcal{H}^{A,B}_{\kappa}}$ is isomorphic to the Cuntz-Krieger algebra $\mathcal{O}_{H_{\kappa}}$ by [12], we see the following theorems.

THEOREM 2.10. The subshift $X_{A,B}^{\kappa}$ of the tiling space is transitive if and if the matrix H_{κ} is irreducible. In this case, H_{κ} satisfies condition (I). Hence if the subshift $X_{A,B}^{\kappa}$ of the tiling space is transitive, the C*-algebra $\mathcal{O}_{\mathcal{H}_{\kappa}^{A,B}}$ is simple and purely infinite.

By Lemma 2.9, we have

THEOREM 2.11. If the matrix A or B is irreducible, the matrix H_{κ} is irreducible and satisfies condition (I), so that the C*-algebra $\mathcal{O}_{\mathcal{H}_{\kappa}^{A,B}}$ is simple and purely infinite.

3. The algebra $\mathcal{O}_{\mathcal{H}^{[N],[M]}}$ for two positive integers N, M

Let *N*, *M* be positive integers with *N*, *M* > 1. They give 1 × 1 commuting matrices *A* = [*N*], *B* = [*M*]. We will present K-theory formulae for the *C**-algebras $\mathcal{O}_{\mathcal{H}_{\kappa}^{[N],[M]}}$ with the exchanging specification κ . In the computations below, we will use the Euclidean algorithm to find order of the torsion part of the *K*₀-group. The directed graph *G*_A for the matrix *A* = [*N*] is a graph consisting of *N*-self directed loops with a vertex denoted by *v*. The *N*-self directed loops are denoted by *E*_A. Similarly the directed graph *G*_B for *B* = [*M*] consists of *M*-self directed loops denoted by *E*_B with the vertex *v*. We fix a specification $\kappa : E_A \times E_B \to E_B \times E_A$ defined by exchanging $\kappa(\alpha, a) = (a, \alpha)$ for $(\alpha, a) \in$ $E_A \times E_B$. Hence $\Omega_{\kappa} = E_A \times E_B$ so that $|\Omega_{\kappa}| = |E_A| \times |E_B| = N \times M$. We then know $A_{\kappa}((\alpha, a), (\delta, b)) = 1$ if and only if b = a, and $B_{\kappa}((\alpha, a), (\beta, d)) = 1$ if and only if $\beta = \alpha$ as in the following figures respectively.

$$\circ \xrightarrow{\alpha} \circ \xrightarrow{\delta} a \downarrow a = b \downarrow a$$

In [12], the K-groups for the case N = 2 and M = 3 have been computed such that

$$K_0(\mathcal{O}_{\mathscr{H}^{[2],[3]}_{\kappa}}) \cong \mathsf{Z}/\mathsf{8Z}, \qquad K_1(\mathcal{O}_{\mathscr{H}^{[2],[3]}_{\kappa}}) \cong 0.$$

Hence $\mathcal{O}_{\mathcal{H}^{[2],[3]}_{\kappa}}$ is stably isomorphic to the Cuntz algebra \mathcal{O}_9 of order 9 ([1]). We will generalize the above computations.

Let I_n be the $n \times n$ identity matrix and E_n the $n \times n$ matrix whose entries are all 1's. For an $N \times N$ -matrix $C = [c_{i,j}]_{i,j=1}^N$ and an $M \times M$ -matrix $D = [d_{k,l}]_{k,l=1}^M$, denote by $C \otimes D$ the $NM \times NM$ matrix

$$C \otimes D = \begin{bmatrix} c_{11}D & c_{12}D & \dots & c_{1N}D \\ c_{21}D & c_{22}D & \dots & c_{2N}D \\ \vdots & \vdots & \ddots & \vdots \\ c_{N1}D & c_{N2}D & \dots & c_{NN}D \end{bmatrix}$$

Hence we have

$$E_{N} \otimes I_{M} = \begin{bmatrix} I_{M} & I_{M} & \dots & I_{M} \\ I_{M} & I_{M} & \dots & I_{M} \\ \vdots & \vdots & \ddots & \vdots \\ I_{M} & I_{M} & \dots & I_{M} \end{bmatrix},$$

$$I_{N} \otimes E_{M} = \begin{bmatrix} E_{M} & 0 & \dots & 0 \\ 0 & E_{M} & \ddots & \vdots \\ \vdots & \ddots & \ddots & 0 \\ 0 & \dots & 0 & E_{M} \end{bmatrix}.$$

We put $E_{[N]} = \{\alpha_1, \ldots, \alpha_N\}, E_{[M]} = \{a_1, \ldots, a_M\}$. As $\Omega_{\kappa} = E_{[N]} \times E_{[M]}$, the basis of $\mathsf{C}^N \otimes \mathsf{C}^M$ are ordered lexicographically from left as in the following way:

(3.1)
$$(\alpha_1, a_1), \dots, (\alpha_1, a_M), (\alpha_2, a_1), \dots, (\alpha_2, a_M), \dots, (\alpha_N, a_1), \dots, (\alpha_N, a_M).$$

Let A_{κ} and B_{κ} be the matrices defined in the previous section for the matrices A = [N], B = [M] with the exchanging specification κ . The following lemma is direct.

LEMMA 3.1. The matrices A_{κ} , B_{κ} are written as

$$A_{\kappa} = E_N \otimes I_M, \qquad B_{\kappa} = I_N \otimes E_M$$

along the ordered basis (3.1). Hence we have

(3.2)
$$A_{\kappa} + B_{\kappa} - I_{NM} = \begin{bmatrix} E_M & I_M & \dots & I_M \\ I_M & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & I_M \\ I_M & \dots & I_M & E_M \end{bmatrix}.$$

We denote by H(0) the matrix $A_{\kappa} + B_{\kappa} - I_{NM}$. By Theorem 2.2, the K-groups of the algebra $\mathcal{O}_{\mathcal{H}_{\kappa}^{[N],[M]}}$ are given by the kernel Ker(H(0)) and the cokernel Coker(H(0)) of the matrix H(0) in Z^{NM} . For an $M \times M$ matrix C and i, j = 1, 2, ..., N with $i \neq j$, define an $N \times N$ block matrix $E_{i,j}(C) = [E_{i,j}(C)(k,l)]_{k,l=1}^N$, whose entries $E_{i,j}(C)(k,l), k, l = 1, 2, ..., N$ are $M \times M$ matrices, by setting

$$\mathsf{E}_{i,j}(C)(k,l) = \begin{cases} I_M & (k=l), \\ C & (k=i, j=l), \\ 0 & \text{else.} \end{cases}$$

The multiplication of the matrix $E_{i,j}(C)$ from the left (resp. right) corresponds to the operation of adding the *C*-multiplication of the *j*th row (resp. *i*th column) to the *i*th row (resp. *j*th column). We will transform H(0) preserving isomorphism classes of the groups Ker(H(0)) and Coker(H(0)) in Z^{NM} by multiplying the matrices $E_{i,j}(C)$, i, j = 1, 2, ..., N.

We first consider row operations and set

$$H(1) = \mathsf{E}_{N-1,N}(-I_M)\mathsf{E}_{N-2,N-1}(-I_M)\cdots\mathsf{E}_{1,2}(-I_M)H(0),$$

$$H(2) = \mathsf{E}_{N,N-1}(I_M)\mathsf{E}_{N-1,N-2}(I_M)\cdots\mathsf{E}_{2,1}(I_M)H(1),$$

$$H(3) = \mathsf{E}_{1,2}(I_M)\mathsf{E}_{2,3}(I_M)\cdots\mathsf{E}_{N-2,N-1}(I_M)\mathsf{E}_{N-1,N}(E_M - I_M)H(2).$$

It is straightforward to see that the matrix H(3) goes to

$$H(3) = \begin{bmatrix} p_M(N-1) & 0 & \dots & 0 \\ p_M(N-2) & E_M - I_M & & \\ \vdots & \vdots & \ddots & \ddots & \vdots \\ p_M(2) & \vdots & \ddots & \\ p_M(1) & E_M - I_M & \dots & E_M - I_M & 0 \\ E_M & I_M & \dots & \dots & I_M & I_M \end{bmatrix}$$

where $p_M(i) = E_M^2 + (i-1)E_M - iI_M = (E_M + iI_M)(E_M - I_M)$ for i = 1, ..., N - 1.

We second consider column operations and set

$$H(4) = H(3)\mathsf{E}_{N,N-1}(-I_M)\mathsf{E}_{N,N-2}(-I_M)\cdots\mathsf{E}_{N,2}(-I_M)\mathsf{E}_{N,1}(-E_M)$$

which goes to

$$H(4) = \begin{bmatrix} p_M(N-1) & 0 & \dots & 0 \\ p_M(N-2) & E_M - I_M & & \\ \vdots & \vdots & \ddots & \ddots & \vdots \\ p_M(2) & \vdots & \ddots & & \\ p_M(1) & E_M - I_M & \dots & E_M - I_M & 0 \\ 0 & 0 & \dots & 0 & I_M \end{bmatrix}.$$

By successive multiplications of the matrices

from the right side of H(4), we obtain the diagonal matrix

$$\tilde{H} = \begin{bmatrix} p_M(N-1) & 0 & \dots & 0 \\ 0 & E_M - I_M & & & \\ & & \ddots & \ddots & & \vdots \\ \vdots & & \ddots & \ddots & & \\ & & & E_M - I_M & 0 \\ 0 & & \dots & 0 & I_M \end{bmatrix}.$$

As $E_M^2 = M E_M$, we have $p_M(N-1) = (M+N-2)E_M - (N-1)I_M$. We thus have

Lemma 3.2.

$$\operatorname{Ker}(A_{\kappa}+B_{\kappa}-I_{NM})$$
 in $\mathsf{Z}^{NM}\cong 0$

and

$$\operatorname{Coker}(A_{\kappa} + B_{\kappa} - I_{NM}) \text{ in } \mathsf{Z}^{NM}$$

$$\cong \overbrace{\mathsf{Z}^{M}/(E_{M} - I_{M})\mathsf{Z}^{M} \oplus \cdots \oplus \mathsf{Z}^{M}/(E_{M} - I_{M})\mathsf{Z}^{M}}^{(N-2)}$$

$$\oplus \mathsf{Z}^{M}/((M + N - 2)E_{M} - (N - 1)I_{M})\mathsf{Z}^{M}.$$

PROOF. It is straightforward to see that the matrix $A_{\kappa} + B_{\kappa} - I_{NM}$ is invertible by the formula (3.2). Since

$$\operatorname{Coker}(A_{\kappa} + B_{\kappa} - I_{NM}) \text{ in } \mathsf{Z}^{NM} \cong \mathsf{Z}^{NM} / \tilde{H} \mathsf{Z}^{NM},$$

the formula for the cokernel is obvious.

We will next compute the following groups to compute $\operatorname{Coker}(A_{\kappa} + B_{\kappa} - I_{NM})$ in Z^{NM} .

(i)
$$Z^M / (E_M - I_M) Z^M$$
,
(ii) $Z^M / ((M + N - 2)E_M - (N - 1)I_M) Z^M$

For an integer *c* and *i*, *j* = 1, 2, ..., *M* with $i \neq j$, define an $M \times M$ matrix $E_{i,j}(c) = [E_{i,j}(c)(k, l)]_{k,l=1}^{M}$ by setting

(3.3)
$$E_{i,j}(c)(k,l) = \begin{cases} 1 & (k=l), \\ c & (k=i, j=l), \\ 0 & \text{else.} \end{cases}$$

(i) By successive multiplications of the matrices

$$E_{M-1,M}(-1)E_{M-2,M-1}(-1)\cdots E_{1,2}(-1),$$

$$E_{M,M-1}(1)E_{M-1,M-2}(1)\cdots E_{2,1}(1),$$

$$E_{M,M-1}(-1)E_{M,M-2}(-1)\cdots E_{M,1}(-1)$$

from the left side of the matrix

$$E_M - I_M = \begin{bmatrix} 0 & 1 & \dots & 1 \\ 1 & 0 & \ddots & \vdots \\ \vdots & \ddots & \ddots & 1 \\ 1 & \dots & 1 & 0 \end{bmatrix},$$

we get the matrix

-1	I	0	•••	0	
-1	0	·	۰.	:	
÷	÷	۰.	1	0	
-1	0		0	1	
M - 1	0		0	0	

which goes to the diagonal matrix with diagonal entries [1, 1, ..., 1, M - 1] by elementary column operations. Hence we see that

(3.4)
$$\mathbf{Z}^M/(E_M - I_M)\mathbf{Z}^M \cong \mathbf{Z}/(M-1)\mathbf{Z}.$$

(ii) Put e = (M + N - 2) - (N - 1) = M - 1 and f = M + N - 2. Then we have

(3.5)
$$(M+N-2)E_M - (N-1)I_M = \begin{bmatrix} e & f & \dots & f \\ f & e & \ddots & \vdots \\ \vdots & \ddots & \ddots & f \\ f & \dots & f & e \end{bmatrix}$$

By a similar manner to the preceding matrix operations from H(1) to H(4), one obtains the following matrix denoted by L(1) from the matrix (3.5)

$$L(1) = \begin{bmatrix} e - f & f - e & 0 & \dots & 0 \\ e - f & 0 & \ddots & \ddots & \vdots \\ \vdots & \vdots & \ddots & f - e & 0 \\ e - f & 0 & \dots & 0 & f - e \\ e & f & \dots & f & f \end{bmatrix}$$

By exchanging columns in the matrix

$$L(1)E_{2,1}(1)E_{3,1}(1)\cdots E_{M,1}(1),$$

we have

$$L(2) = \begin{bmatrix} f - e & 0 & \dots & 0 & 0 \\ 0 & \ddots & \ddots & \vdots & \vdots \\ \vdots & \ddots & f - e & 0 & 0 \\ 0 & \dots & 0 & f - e & 0 \\ f & \dots & f & f & e + (M - 1)f \end{bmatrix}$$

It is easy to see that the matrix

$$E_{M-1,M-2}(1)\cdots E_{3,2}(1)E_{2,1}(1)L(2)E_{2,1}(-1)E_{3,2}(-1)\cdots E_{M-1,M-2}(-1)$$

goes to

$$\tilde{L} = \begin{bmatrix} f - e & 0 & \dots & \dots & 0 \\ 0 & \ddots & \ddots & & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ 0 & \dots & 0 & f - e & 0 \\ 0 & \dots & 0 & f & e + (M - 1)f \end{bmatrix}$$

•

Put the 2 \times 2 matrix $L_{(N,M)}$ by setting

$$L_{(N,M)} = \begin{bmatrix} f - e & 0\\ f & e + (M - 1)f \end{bmatrix}.$$

As f - e = N - 1, we have the following lemma with (3.4).

Lemma 3.3.

(i)
$$\mathbf{Z}^{M}/(E_{M}-I_{M})\mathbf{Z}^{M} \cong \mathbf{Z}/(M-1)\mathbf{Z}.$$

(ii) $\mathbf{Z}^{M}/((M+N-2)E_{M}-(N-1)I_{M})\mathbf{Z}^{M}$

$$\cong \overbrace{\mathbf{Z}/(N-1)\mathbf{Z} \oplus \cdots \oplus \mathbf{Z}/(N-1)\mathbf{Z}}^{M-2} \oplus \mathbf{Z}^{2}/L_{(N,M)}\mathbf{Z}^{2}.$$

It remains to compute the group $Z^2/L_{(N,M)}Z^2$. Put n = N - 1, m = M - 1. As f - e = n and f = m + n, we have e + (M - 1)f = (M - 1)(M + N - 1) = m(m + n + 1) so that

$$L_{(N,M)} = \begin{bmatrix} n & 0\\ n+m & m(m+n+1) \end{bmatrix}.$$

For an integer *c* and *i*, j = 1, 2 with $i \neq j$, define an 2×2 matrix $E_{i,j}(c) = [E_{i,j}(c)(k,l)]_{k,l=1}^2$ in a similar way to (3.3). Put $L_{n,m} = E_{2,1}(-1)L_{(N,M)}$ so that

$$L_{n,m} = \begin{bmatrix} n & 0 \\ m & m(m+n+1) \end{bmatrix}.$$

We may assume that $M \ge N$ and hence $m \ge n$.

If *m* is divided by *n* so that m = nk for some $k \in N$, the matrix $E_{2,1}(-k)L_{n,m}$ goes to the diagonal matrix:

$$\begin{bmatrix} n & 0 \\ 0 & m(m+n+1) \end{bmatrix} = \begin{bmatrix} N-1 & 0 \\ 0 & (M-1)(M+N-1) \end{bmatrix}.$$

Hence we have

$$\mathsf{Z}^2/L_{(N,M)}\mathsf{Z}^2 \cong \mathsf{Z}/(N-1)\mathsf{Z} \ \oplus \ \mathsf{Z}/(M-1)(M+N-1)\mathsf{Z}.$$

Otherwise, by the Euclidean algorithm, we have lists of integers r_0, r_1, \ldots, r_j and $k_0, k_1, \ldots, k_{j+1}$ for some $j \in N$ such that

$$\begin{split} m &= nk_0 + r_0, & 0 < r_0 < n, \\ n &= r_0k_1 + r_1, & 0 < r_1 < r_0, \\ r_0 &= r_1k_2 + r_2, & 0 < r_2 < r_1, \\ \dots & \dots & \dots \\ r_{j-2} &= r_{j-1}k_j + r_j, & 0 < r_j < r_{j-1}, \\ r_{j-1} &= r_jk_{j+1}, & 0 = r_{j+1} \end{split}$$

where $r_j = (m, n)$ the greatest common divisor of *m* and *n*. Put g = m(m + n + 1). We set

$$L_{n,m}(0) = E_{2,1}(-k_0)L_{n,m} = \begin{bmatrix} n & 0 \\ r_0 & g \end{bmatrix}.$$

We define a finite sequence of matrices $L_{n,m}(l)$, l = 1, 2, ... by

$$L_{n,m}(1) = E_{1,2}(-k_1)L_{n,m}(0), \qquad L_{n,m}(2) = E_{2,1}(-k_2)L_{n,m}(1)$$

and inductively

$$L_{n,m}(2i-1) = E_{1,2}(-k_{2i-1})L_{n,m}(2i-2),$$
$$L_{n,m}(2i) = E_{2,1}(-k_{2i})L_{n,m}(2i-1).$$

The Euclidean algorithm stops at j + 1 = 2i - 1 or j + 1 = 2i for some $i \in N$. We set

$$[k_0] = 1, \quad [k_1] = k_1, \quad [k_1, k_2] = 1 + k_1 k_2, \quad [k_1, k_2, k_3] = [k_1, k_2] k_3 + [k_1],$$

...,
$$[k_1, k_2, \dots, k_{j+1}] = [k_1, k_2, \dots, k_j] k_{j+1} + [k_1, \dots, k_{j-1}].$$

Then we have

$$L_{n,m}(1) = \begin{bmatrix} r_1 & -[k_1]g \\ r_0 & g \end{bmatrix}, \qquad L_{n,m}(2) = \begin{bmatrix} r_1 & -[k_1]g \\ r_2 & [k_1, k_2]g \end{bmatrix},$$

and inductively

$$L_{n,m}(2i-1) = \begin{bmatrix} r_{2i-1} & -[k_1, k_2, \dots, k_{2i-1}]g \\ r_{2i-2} & [k_1, k_2, \dots, k_{2i-2}]g \end{bmatrix},$$
$$L_{n,m}(2i) = \begin{bmatrix} r_{2i-1} & -[k_1, k_2, \dots, k_{2i-1}]g \\ r_{2i} & [k_1, k_2, \dots, k_{2i}]g \end{bmatrix}$$

for i = 1, 2, ... We denote by d the greatest common divisor (m, n) of m and n, so that $d = r_j$. Take $m_0 \in Z$ such that $m = m_0 d$. Put $g_0 = m_0(m + n + 1)$ so that $g = g_0 d$. We have two cases.

Case 1: j + 1 = 2i - 1 for some $i \in N$. We have

$$L_{n,m}(j+1) = \begin{bmatrix} r_{j+1} & -[k_1, k_2, \dots, k_{j+1}]g \\ r_j & [k_1, k_2, \dots, k_j]g \end{bmatrix} = \begin{bmatrix} 0 & -[k_1, k_2, \dots, k_{j+1}]g \\ d & [k_1, k_2, \dots, k_j]g_0d \end{bmatrix}$$

and hence

$$L_{n,m}(j+1)E_{1,2}(-[k_1,k_2,\ldots,k_j]g_0) = \begin{bmatrix} 0 & -[k_1,k_2,\ldots,k_{j+1}]g\\d & 0 \end{bmatrix}.$$

Case 2: j + 1 = 2i for some $i \in N$. We have

$$L_{n,m}(j+1) = \begin{bmatrix} r_j & -[k_1, k_2, \dots, k_j]g\\ r_{j+1} & [k_1, k_2, \dots, k_{j+1}]g \end{bmatrix} = \begin{bmatrix} d & -[k_1, k_2, \dots, k_j]g_0d\\ 0 & [k_1, k_2, \dots, k_{j+1}]g \end{bmatrix}$$

and hence

$$L_{n,m}(j+1)E_{1,2}([k_1,k_2,\ldots,k_j]g_0) = \begin{bmatrix} d & 0\\ 0 & [k_1,k_2,\ldots,k_{j+1}]g \end{bmatrix}.$$

We reach the following lemma.

Lemma 3.4.

$$\mathsf{Z}^2/L_{(N,M)}\mathsf{Z}^2 \cong \mathsf{Z}/d\mathsf{Z} \oplus \mathsf{Z}/[k_1, k_2, \dots, k_{j+1}]g\mathsf{Z}.$$

Therefore we have

THEOREM 3.5. For positive integers $1 < N \leq M \in \mathbb{N}$ and the exchanging specification κ between N-loops and M-loops in a graph with one vertex, the

 C^* -algebra $\mathcal{O}_{\mathcal{H}^{[N],[M]}_k}$ is a simple purely infinite Cuntz-Krieger algebra whose K-groups are

$$K_{1}(\mathcal{O}_{\mathscr{H}_{\kappa}^{[N],[M]}}) \cong 0,$$

$$K_{0}(\mathcal{O}_{\mathscr{H}_{\kappa}^{[N],[M]}}) \cong \overbrace{\mathsf{Z}/(N-1)\mathsf{Z} \oplus \cdots \oplus \mathsf{Z}/(N-1)\mathsf{Z}}^{M-2}$$

$$\oplus \overbrace{\mathsf{Z}/(M-1)\mathsf{Z} \oplus \cdots \oplus \mathsf{Z}/(M-1)\mathsf{Z}}^{N-2}$$

$$\oplus [\mathsf{Z}/d\mathsf{Z} \oplus \mathsf{Z}/[k_{1}, k_{2}, \dots, k_{j+1}](M-1)(M+N-1)\mathsf{Z}]$$

where d = (N - 1, M - 1) is the greatest common divisor of N - 1 and M - 1, the sequence $k_0, k_1, \ldots, k_{j+1}$ of integers is the list of the successive integral quotients of M - 1 by N - 1 in the Euclidean algorithm such as

$$\begin{split} M-1 &= (N-1)k_0 + r_0 & for some \quad k_0 \in \mathsf{Z}_+, \ 0 < r_0 < N-1, \\ N-1 &= r_0k_1 + r_1 & for some \quad k_1 \in \mathsf{Z}_+, \ 0 < r_1 < r_0, \\ \vdots \\ r_{j-2} &= r_{j-1}k_j + r_j & for some \quad k_j \in \mathsf{Z}_+, \ 0 < r_j < r_{j-1}, \\ r_{j-1} &= dk_{j+1}, \end{split}$$

and the integer $[k_1, k_2, ..., k_{j+1}]$ is defined by inductively

$$[k_0] = 1, \quad [k_1] = k_1, \quad [k_1, k_2] = 1 + k_1 k_2,$$

...,
$$[k_1, k_2, \dots, k_{j+1}] = [k_1, k_2, \dots, k_j] k_{j+1} + [k_1, \dots, k_{j-1}].$$

We finally present examples.

EXAMPLES 3.6. 1. For the case 1 < N = M, we have d = N - 1, $k_0 = 1$, $r_0 = 0$. As we see $[k_1, ..., k_{j+1}] = 1$, we have

$$[k_1, \ldots, k_{j+1}](M-1)(M+N-1) = (N-1)(2N-1).$$

Hence

$$K_0(\mathcal{O}_{\mathcal{H}_{\kappa}^{[N],[N]}}) \cong \overbrace{\mathsf{Z}/(N-1)\mathsf{Z} \oplus \cdots \oplus \mathsf{Z}/(N-1)\mathsf{Z}}^{2N-3} \oplus \mathsf{Z}/(N-1)(2N-1)\mathsf{Z}.$$

2. For the case N = 2 and $M \ge 2$, we have $d = 1, r_0 = 0$. As we see $[k_1, ..., k_{j+1}] = 1$, we have

$$[k_1, \ldots, k_{j+1}](M-1)(M+N-1) = 1 \times (M-1)(M+1) = M^2 - 1.$$

Hence

$$K_0(\mathcal{O}_{\mathcal{H}^{[2],[M]}}) \cong \mathsf{Z}/(M^2 - 1)\mathsf{Z}.$$

The formula for N = 2, M = 3 is already seen in [12].

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