# A GENERALIZATION OF THE ANNULUS FORMULA FOR THE RELATIVE EXTREMAL FUNCTION 

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#### Abstract

The main result of this paper is an annulus formula for the relative extremal function in the context of Stein spaces (Theorem 1.1). It has an application in the theory of extensions of holomorphic functions defined on generalized crosses in products of Stein spaces (Theorem 4.6).


## 1. Introduction

For an open subset $D$ of a complex space $X$ and any subset $A \subset D$ denote by $h_{A, D}^{\star}$ the relative extremal function of $A$ with respect to $D$, i.e. the standard upper semicontinuous regularization of the function

$$
h_{A, D}:=\sup \left\{u: u \in \mathscr{P} \mathscr{S} \mathscr{H}(D), u \leq 1,\left.u\right|_{A} \leq 0\right\}
$$

where $\mathscr{P} \mathscr{S} \mathscr{H}(D)$ stands for the family of all plurisubharmonic functions on D.

The relative extremal function is a very important object in complex analysis. If one has either an explicit formula for the relative extremal function or a geometric description of its sublevel sets, then it is possible to find estimates for bounded holomorphic functions on $D$ satisfying some growth estimate on $A$ - to recall, for example, the two constants theorem ([12], Proposition 3.2.4).

For a number $r \in(0,1]$ define the sublevel sets of the relative extremal function

$$
\begin{aligned}
\Delta(r) & :=\left\{z \in D: h_{A, D}^{\star}(z)<r\right\}, \\
\Delta[r] & :=\left\{z \in D: h_{A, D}^{\star}(z) \leq r\right\} .
\end{aligned}
$$

An annulus with respect to the pair $(A, D)$ is defined as a set of the form $\Delta(s) \backslash \Delta[r]$ for $0<r<s \leq 1$. This justifies the name "annulus formula".

In [11] Jarnicki and Pflug proved a Hartogs type extension theorem for ( $N, k$ )-crosses lying in the product of Riemann domains of holomorphy over

[^0]$\mathrm{C}^{n}$, which is a generalization of the classical cross theorem (see, for example [2]). The key role in their proof is played by an annulus formula for the relative extremal function. The aim of the present paper is to extend that formula to the situation, where instead of the Riemann domains of holomorphy over $\mathrm{C}^{n}$ we consider Stein spaces. Namely, we shall prove the following

Theorem 1.1. Let $D \subset \subset X$, where for the couple $(D, X)$ at least one of the following two conditions is satisfied:
(1) $D$ is a union of an increasing sequence of irreducible, locally irreducible, weakly parabolic Stein spaces and $X$ is a Stein space,
(2) $D$ is a union of an increasing sequence of Stein manifolds and $X$ is a Josefson manifold.
Let $A \subset D$ be nonpluripolar. Then for $0<r<s \leq 1$ we have

$$
h_{\Delta(r), \Delta(s)}^{\star}=\max \left\{0, \frac{h_{A, D}^{\star}-r}{s-r}\right\} \quad \text { on } \quad \Delta(s)
$$

Note that the class of Josefson manifolds (i.e. those complex manifolds, for which any locally pluripolar set is globally pluripolar) is essentialy wider than the class of Stein manifolds (see [3], Theorem 5.3).

It is also well known that the limit of an increasing sequence of Stein manifolds need not to be Stein (see, for example, [7]). It is an open problem whether our result holds true for arbitrary complex manifolds or spaces.

The proof of Theorem 1.1 is somewhat similar to the one given in [11]. However, in some places (especially when the assumption (1) is under consideration; Steps 4 and 6) it is essentially different, since the argument must be much more subtle: the required approximation of a set $A$ is here far away from being as natural as in the case of Riemann domains over $\mathrm{C}^{n}$.

Our main result will also allow us (see Section 4) to prove the formula for the relatively extremal function of the envelope of $(N, k-1)$-cross with respect to the envelope of ( $N, k$ )-cross (Theorem 4.3; cf. [11]). Finally we use our main result to give a new Hartogs type extension theorem for the generalized ( $N, k$ )-crosses (introduced in [14]) in the context of Stein manifolds. In the author's intention the present paper is a step towards the extenstion of separately holomorphic functions on the generalized ( $N, k$ )-crosses in the context of arbitrary complex manifolds, or even complex spaces.

The paper was written during the author's stay at the Carl von Ossietzky Universität Oldenburg. The author would like to express his gratitude to Professor Peter Pflug for his constant help and inspiring discussions.

## 2. Prerequisites

This section contains some definitions and results which will be needed in the sequel.

We assume that any complex space $X$ considered here is reduced, has a countable basis of topology and is of pure dimension. If $X$ is a complex space, then any $x \in X$ possesses an open neighborhood $U$ and a biholomorphic mapping $\varphi$ from $U$ to some subvariety $B$ of a domain $V \subset C^{n}$. The 4-tuple $(U, \varphi, B, V)$ will be called a chart of $X$. Also, we will use the notation Reg $X$ for the set of all regular points of $X$ and $\operatorname{Sing} X$ for the set of all singular points of $X$ (see [15], Chapter V). In the present paper $\mathscr{P} \mathscr{L} \mathscr{P}(X)$ stands for the family of all (locally) pluripolar subsets of $X$ and $\mathscr{O}(X)$ is the space of all holomorphic functions on $X$. Finally, we assume throughout the paper that any appearing complex manifold is countable at infinity.

Definition 2.1. Let $X$ be a complex space. A function $u: X \rightarrow[-\infty, \infty)$, $u \not \equiv-\infty$ on irreducible componnents of $X$, is called plurisubharmonic (written $u \in \mathscr{P} \mathscr{S} \mathscr{H}(X))$ if for any $x \in X$ there are a chart $(U, \varphi, B, V)$ with $x \in U$ and a function $\psi \in \mathscr{P} \mathscr{S} \mathscr{H}(V)$ with $\psi \circ \varphi=\left.u\right|_{U}$.

Definition 2.2 ([9], Chapter VII, Section A). Let $X$ be a complex space and let $K \subset X$ be compact. The holomorphically convex hull of $K$ in $X$ is defined as

$$
\hat{K}_{X}:=\left\{x \in X:|f(x)| \leq\|f\|_{K}, f \in \mathcal{O}(X)\right\} .
$$

We say that $K$ is holomorphically convex, if $K=\hat{K}_{X}$. A complex space $X$ is called holomorphically convex, if for any compact set $K \subset X$, the set $\hat{K}_{X}$ is also compact.

Theorem 2.3 ([16]). Let X be a Stein space (see [9], Chapter VII, Section A, Definition 2). Then there exists a real analytic, strongly plurisubharmonic exhaustion function on $X$.

Note that the real analyticity of a function on a complex space $X$ is defined in a similar way like the plurisubharmonicity. A function $f$ on $X$ is real analytic, if for any $x \in X$ there are a chart $(U, \varphi, B, V)$ with $x \in U$ and a real analytic function $g$ on $V$ with $g \circ \varphi=\left.f\right|_{U}$ (see [16]).

For a function $\psi$ as in Theorem 2.3 and for any real number $c$ denote by $\Omega_{c}(\psi)$ the sublevel set $\{x \in X: \psi(x)<c\}$.

Definition 2.4 ([2]). We say that a set $A \subset X$ is pluriregular at a point $a \in \bar{A}$ if $h_{A \cap U, U}^{\star}(a)=0$ for any open neighborhood $U$ of $a$. Define

$$
A^{\star}:=\{a \in \bar{A}: A \text { is pluriregular at } a\} .
$$

We say that $A$ is locally pluriregular if $A \neq \emptyset$ and $A$ is pluriregular at each of its points, i.e. $\emptyset \neq A \subset A^{\star}$.

Lemma 2.5 (cf. [12], Propostion 3.2.27, Lemma 6.1.1). Let $X$ be a complex space, $A \subset X$ locally pluriregular, and $\varepsilon \in(0,1)$. Put

$$
X_{\varepsilon}:=\left\{z \in X: h_{A, X}^{\star}(z)<1-\varepsilon\right\} .
$$

Then for any connected component $D$ of $X_{\varepsilon}$ we have
(1) $A \cap D \neq \emptyset$.
(2) $h_{A \cap D, D}^{\star}(z)=\frac{h_{A, X}^{\star}(z)}{1-\varepsilon}, z \in D$.

Proof. The proof goes along the same lines as the proof of Proposition 3.2.27 from [12]. We only need to observe that by virtue of Theorem 5.3.1 from [8], Proposition 2.3.6 from [12] is also true in our context.

Proposition 2.6 (cf. [12], Proposition 3.2.23). Let $X_{k} \nearrow X \subset \subset Y$, where $X$ is a complex space and $Y$ is a complex space for which Josefson's theorem is valid, let $A_{k} \subset X_{k}, A_{k} \nearrow$ A. Then $h_{A_{k}, X_{k}}^{\star} \searrow h_{A, X}^{\star}$.

Proof. The proof is the same as the one of Proposition 3.2.23 in [12]; only, we use Lemma 2.2 from [1] instead of Corollary 3.2.12.

Proposition 2.7 (cf. [12], Proposition 3.2.15). Let $Y$ be an irreducible Stein space. Let $X=\Omega_{c}(\psi)$ with some $c \in \mathrm{R}$ and $\psi$ as in Theorem 2.3 for $Y$, and let $A \subset X$. Then for any $\varepsilon \in(0,1)$ we have

$$
\frac{h_{A, X}^{\star}-\varepsilon}{1-\varepsilon} \leq h_{\Delta(\varepsilon), X}^{\star} \leq h_{A, X}^{\star}
$$

Proof. The proof is the same as the proof of Proposition 3.2.15 from [12]. We only need to use Lemma 2.6 and Theorem 2.1 from [1] instead of Proposition 3.2.2 and Proposition 3.2.11, respectively.

Proposition 2.8 (cf. [13], Proposition 4.5.2). Let $Y$ be an irreducible Stein space. Let $X=\Omega_{c}(\psi)$ with some $c \in \mathrm{R}$ and $\psi$ as in Theorem 2.3 for $Y$, and let $A \subset X$ be relatively compact. Then, for any point $x_{0} \in \partial X$ we have $\lim _{X \ni x \rightarrow x_{0}} h_{A, X}(x)=1$.

Proof. The proof is as the one given in [13], since it depends only on the existence of an exhaustion function for $X$.

Proposition 2.9 (cf. [12], Proposition 3.2.24). Let $X$ be a Stein space and let $\left(K_{j}\right)_{j \in \mathrm{~N}}$ be a decreasing sequence of compact subsets of $X$ with $\bigcap_{j \in \mathrm{~N}} K_{j}=K$. Then $h_{K_{j}, X} \nearrow h_{K, X}$.

Proof. The proof may be rewritten verbatim from [12].
The complex Monge-Ampère operator $\left(d d^{c} u\right)^{n}$ for a locally bounded function $u \in \mathscr{P} \mathscr{S} \mathscr{H}(X)$ is defined in a standard way on $\operatorname{Reg} X$ ([4]) and it is extended "by zero" through Sing $X$ (for the details and the further theory see [3]).

Note that (see [2]) if $D$ is hyperconvex (i.e. there exists a plurisubharmonic negative function $\eta$ such that for any $c<0$ the set $\{z \in D: \eta(z)<c\}$ is relatively compact in $D$ ) and $A$ is compact, then $\left(d d^{c} h_{A, D}^{\star}\right)^{n}=0$ on $D \backslash A$.

Theorem 2.10 (cf. [12], Theorem 3.2.32, [13], Corollary 3.7.4). Let $\Omega \subset \subset$ $D \subset \subset X$, where $X$ is a Stein space, $D=\Omega_{c}(\psi)$ with some $c \in \mathrm{R}$ and $\psi$ as in Theorem 2.3 for $X$, and $\Omega$ is an open set. Let $u, v \in \mathscr{P} \mathscr{S} \mathscr{H}(\Omega) \cap L^{\infty}(\Omega)$ such that $\left(d d^{c} v\right)^{n} \geq\left(d d^{c} u\right)^{n}$ on $\Omega$ and

$$
\liminf _{\Omega \ni z \rightarrow z_{0}}(u(z)-v(z)) \geq 0, \quad z_{0} \in \partial \Omega
$$

Then $u \geq v$ on $\Omega$.
Proof. Observe that $\eta:=\psi-c<0$ is a real analytic strongly plurisubharmonic exhaustion function for $D$. Then there is some $C<0$ satisfying $\bar{\Omega} \subset\{\eta<C\}$. If now $\{u<v\} \neq \emptyset$, then also $S:=\{u<v+\varepsilon \eta\}$ is nonempty for some $\varepsilon>0$. Moreover, the set $S \cap \operatorname{Reg} D$ is of positive Lebesgue measure. Also, $\{u \leq v+\varepsilon \eta\}$ has to be relatively compact in $\Omega$. Hence we get

$$
\int_{S}\left(d d^{c} u\right)^{n} \geq \int_{S}\left(d d^{c}(v+\varepsilon \eta)\right)^{n} \geq \int_{S}\left(d d^{c} v\right)^{n}+\varepsilon^{n} \int_{S}\left(d d^{c} \eta\right)^{n}>\int_{S}\left(d d^{c} v\right)^{n}
$$

a contradiction (note that the first inequality above is the consequence of Theorem 4.3 from [3]).

Theorem 2.11 (cf. [12], Corollary 3.2.33). Let $X$ be a Stein space, $D=$ $\Omega_{c}(\psi)$ with some $c \in \mathrm{R}$ and $\psi$ as in Theorem 2.3 for $X, K \subset \subset D$ compact, and let $U \subset D \backslash K$ be open. Assume that $h_{K, D}^{\star}$ is continuous and let $u \in$ $\mathscr{P} \mathscr{S} \mathscr{H}(U) \cap L^{\infty}(U), u \leq 1$ and such that

$$
\liminf _{U \ni z \rightarrow z_{0}}\left(h_{K, D}^{\star}(z)-u(z)\right) \geq 0, \quad z_{0} \in \partial U \cap D
$$

Then $u \leq h_{K, D}^{\star}$ in $U$.
Proof. We know that $\left(d d^{c} h_{K, D}^{\star}\right)^{n}=0$ on $D \backslash K$. In particular, $\left(d d^{c} h_{K, D}^{\star}\right)^{n}$ $\leq\left(d d^{c} u\right)^{n}$ in $U$. Moreover, $\lim _{z \rightarrow z_{0}} h_{K, D}^{\star}=1, z_{0} \in \partial D$. Using Theorem 2.10 we get the conclusion.

Definition 2.12 (see [20], [21]). Let $X$ be an irreducible Stein space. Then $X$ is called weakly parabolic if there exists a plurisubharmonic continuous
exhaustion function $g: X \rightarrow[0, \infty)$ such that $\log g$ is plurisubharmonic and satisfies $\left(d d^{c} \log g\right)^{n}=0$ on $X \backslash g^{-1}(0)$.

Theorem 2.13 (see [22], Theorème 3.16). Let $X$ be an irreducible, locally irreducible weakly parabolic Stein space with some potential $g$, let $K \subset X$ be compact and let $U \subset X$ be an open neighborhood of $\hat{K}_{X}$. Then there exists a compact, holomorphically convex and locally L-regular (see [22], Definition 3.13) set $E$ with $\hat{K}_{X} \subset E \subset U$.

## 3. Proof of the main result

First (Steps 1-4) we show that if we know the conclusion holds true for compact sets $A$ (and holomorphically convex, while we consider assumption (1)), then we are able to prove the theorem in its full generality. In Steps 5 and 6 we show that theorem is true for compact sets $A$. In this purpose we use the approximation of $A$ from above by compacta (holomorphically convex, when we work with assumption (1)) with continuous relative extremal functions. The argument however must be more delicate than the one given in [11], where such approximation do not require the holomorphic convexity, and additionally, it is given just by the $\varepsilon$-envelopes of a set $A$.

Using Proposition 2.6 we may reduce the proof to the situation where our assumptions are as follows:
(1) $D$ is an irreducible, locally irreducible, weakly parabolic Stein space and $X$ is a Stein space,
(2) $D$ is a Stein manifold and $X$ is a Josefson manifold.

Proof of Theorem 1.1. Fix $0<r<s \leq 1$ and put

$$
L:=h_{\Delta(r), \Delta(s)}^{\star}, \quad R:=\max \left\{0, \frac{h_{A, D}^{\star}-r}{s-r}\right\}
$$

Observe that $L \geq R$. Thus we only need to prove the opposite inequality.
Step 1. We may assume that $s=1$.
The proof of Step 1 is the same for both assumptions, (1) and (2). Take $0<r<s<1$. Then $A \cap S$ is nonpluripolar for any connected component $S$ of $\Delta(s)$, and there is $h_{A, \Delta(s)}^{\star}=(1 / s) h_{A, D}^{\star}$ on $\Delta(s)$ (this is because of Lemma 2.5 and the fact that for $D$ as in the assumptions, thanks to Josefson's theorem, we have that for any $P \in \mathscr{P} \mathscr{L} \mathscr{P}(D)$ there exists a $u \in \mathscr{P} \mathscr{S} \mathscr{H}(D), u \leq 0$ and nonconstant, such that $P \subset\{u=-\infty\}$, from which follows that $h_{A \cup P, D}^{\star}=$ $h_{A, D}^{\star}$ for any $A \subset D$ and pluripolar set $P$ (see [1], Theorem 2.1). Finally, $A \backslash A^{\star}$ is pluripolar - see Lemma 2.6 from [1]). As a consequence, we get
$L=h_{\Delta(r), \Delta(s)}=h_{\left\{h_{A, \Delta(s)}^{\star}<\frac{r}{s}\right\}, \Delta(s)}, R=\max \left\{0, \frac{h_{A, \Delta(s)}^{\star}-\frac{r}{s}}{1-\frac{r}{s}}\right\}$. Thus, the problem for the data ( $D, A, r, s$ ) is done if only it is done for the data ( $S, A \cap S, \frac{r}{s}, 1$ ), where $S$ is as above.

Step 2. Approximation. Let $A_{v} \nearrow A, D_{v} \nearrow D$, where $A_{v} \subset D_{v}$ is nonpluripolar for each $\nu \in \mathrm{N}$. Then, if the conclusion holds true for the data $\left(D_{v}, A_{v}, r, 1\right), v \in \mathrm{~N}$, then it holds true for ( $D, A, r, 1$ ), as well.

Indeed, $h_{A_{v}, D_{v}}^{\star} \searrow h_{A, D}^{\star}$ (by virtue of Proposition 2.6). Hence $\left\{h_{A_{v}, D_{v}}^{\star}<\right.$ $r\} \nearrow \Delta(r)$ and $h_{\left\{h_{A_{v}, D_{\nu}}^{\star}<r\right\}, D}^{\star} \searrow h_{\Delta(r), D}^{\star}$.

Using Step 1 and Step 2, from now on we assume that $A \subset \subset D$ and instead of $D$ we consider $\Omega_{c}(\psi)$, some sublevel set of a real analytic strongly plurisubharmonic exhaustion function of $D$.

Step 3. Assume that the condition (2) is satisfied. Then, if the conclusion holds true for all nonpluripolar compact sets $A$, then it holds also for all nonpluripolar sets $A$.

Indeed, by Step 2, the conclusion holds for all non-empty open sets $A$. Take a nonpluripolar set $A$. Since the set $\Delta(\varepsilon)$ is open, we have

$$
h_{\left\{h_{\Delta(\varepsilon), D}^{\star}<r\right\}, D}^{\star}=\max \left\{0, \frac{h_{\Delta(\varepsilon), D}^{\star}-r}{1-r}\right\}, \quad \varepsilon \in(0,1)
$$

Then $\frac{h_{A, D}^{\star}-\varepsilon}{1-\varepsilon} \leq h_{\Delta(\varepsilon), D}^{\star} \leq h_{A, D}^{\star}$ (because of Proposition 2.7), from which follows $h_{\Delta(\varepsilon), D}^{\star} \nearrow h_{A, D}^{\star}$ as $\varepsilon \searrow 0$. Moreover,

$$
\left\{h_{\Delta(\varepsilon), D}^{\star}<\frac{r-\varepsilon}{1-\varepsilon}\right\} \subset \Delta(r) \subset\left\{h_{\Delta(\varepsilon), D}^{\star}<r\right\}, \quad \varepsilon \in(0, r)
$$

which implies

$$
\max \left\{0, \frac{h_{\Delta(\varepsilon), D}^{\star}-\frac{r-\varepsilon}{1-\varepsilon}}{1-\frac{r-\varepsilon}{1-\varepsilon}}\right\} \geq h_{\Delta(r), D}^{\star} \geq \max \left\{0, \frac{h_{\Delta(\varepsilon), D}^{\star}-r}{1-r}\right\}, \quad \varepsilon \in(0, r),
$$

and we get the conclusion as $\varepsilon \searrow 0$.
Thus the proof under assumptions of (2) reduces to the case where $A$ is compact.

Step 4. Assume that the condition (1) is satisfied. Then, if theorem holds true for all nonpluripolar compact and holomorphically convex sets $A$, then it holds true for all nonpluripolar sets $A$.

Take a nonpluripolar set $A$. The set $\Delta(\varepsilon)$ is Runge in $D$ (that is, for any compact set $K \subset \Delta(\varepsilon)$, the set $\hat{K}_{X} \cap \Delta(\varepsilon)$ is compact, see [17]) and in particular it is a Stein space (see [8], Theorem 5.4), so using approximation by
compact holomorphically convex sets we see that the result holds true for the sets $A=\Delta(\varepsilon)$. We finish the proof of Step 4 as in the Step 3.

Step 5. The case where $A$ is compact and $h_{A, D}^{\star}$ is continuous.
The proof is parallel for both assumptions, (1) and (2). The set $\Delta[r]$ is compact (by virtue of the continuity of $h_{A, D}^{\star}$ and Proposition 2.8). Let $u \in$ $\mathscr{P} \mathscr{S} \mathscr{H}(D), u \leq 1, u \leq 0$ on $\Delta[r]$. Put $U:=D \backslash \Delta[r]$. Then for a $z_{0} \in \partial U$ we obtain

$$
\liminf _{U \ni z \rightarrow z_{0}}\left(h_{A, D}^{\star}(z)-(1-r) u(z)-r\right) \geq 0 .
$$

Hence $(1-r) u+r \leq h_{A, D}^{\star}$ in $U$ (see Theorem 2.11). Thus $h_{\Delta[r], D} \leq R$ and $h_{\Delta[r], D}^{\star} \equiv R$. Finally, considering a sequence of positive numbers $\left(r_{i}\right)_{i \in \mathrm{~N}}$ increasing to $r$ we get $L \equiv R$.

Step 6. The case where $A$ is compact.
First we carry out a construction of a decreasing sequence $\left(A_{j}\right)_{j \in N}$ of closed sets containing $A$, and being a finite unions of closed "balls".

Since $D$ is metrizable (for both assumptions, (1) and (2), by virtue of Urysohn's Metrization Theorem), there exists a metric $d$, which gives the topology of $D$.

In the case where $D$ is a Stein space take a finite set of charts $\left(U_{i}, \varphi_{i}, B_{i}, V_{i}\right)$, $i=1, \ldots, s$, and corresponding sets $\hat{\mathrm{B}}\left(a_{i}, r_{i}\right)$, such that $\hat{\mathrm{B}}\left(a_{i}, r_{i}\right) \subset \subset U_{i}$ and $\varphi_{i}: \hat{\mathrm{B}}\left(a_{i}, r_{i}\right) \rightarrow B_{i} \cap \mathrm{~B}\left(\varphi_{i}\left(a_{i}\right), r_{i}\right) \subset \subset V_{i}$ is a biholomorphism, $i=1, \ldots, s$, satisfying $A \subset \bigcup_{i=1}^{s} \hat{\mathrm{~B}}\left(a_{i}, r_{i}\right)$.

We construct a set $A_{1}$. Fix an $a \in A$. Without loss of generality we may assume that $a \in \hat{\mathrm{~B}}\left(a_{1}, r_{1}\right) \subset U_{1}$. Take a number $r_{a}<1$ with $\mathrm{B}\left(\varphi_{1}(a), r_{a}\right) \subset$ $\mathrm{B}\left(\varphi_{1}\left(a_{1}\right), r_{1}\right)$ and small enough so that $\hat{\mathrm{B}}\left(a, r_{a}\right)=\varphi_{1}^{-1}\left(B_{1} \cap \mathrm{~B}\left(\varphi_{1}(a), r_{a}\right)\right) \subset$ $\{x \in D: d(x, A) \leq 1\}$. We may now choose a finite number of sets $\hat{\mathrm{B}}\left(a_{l}^{1}, r_{a_{l}^{1}}\right), l=1, \ldots, s_{1}$, with $a_{l}^{1} \in A, l=1, \ldots, s_{1}$, and such that $A \subset$ $\bigcup_{l=1}^{s_{1}} \hat{\mathrm{~B}}\left(a_{l}^{1}, r_{a_{l}^{1}}\right)$, and define $A_{1}:=\bigcup_{l=1}^{s_{1}} \overline{\hat{\mathrm{~B}}\left(a_{l}^{1}, r_{a_{l}^{1}}\right)}$.

Suppose we have constructed the set $A_{j}$ for some $j \in \mathrm{~N}$. Then we obtain $A_{j+1}$ as follows: take an $a \in A$ and - as before - assume that $a \in$ $\hat{\mathrm{B}}\left(a_{1}^{j}, r_{a_{1}^{j}}\right) \subset A_{j} \cap U_{i_{a}}$ for some $i_{a} \in\{1, \ldots, s\}$. Take a number $r_{a}<\frac{1}{j+1}$ such that $\mathrm{B}\left(\varphi_{i_{a}}(a), r_{a}\right) \subset \mathrm{B}\left(\varphi_{i_{a}}\left(a_{1}^{j}\right), r_{a_{1}^{j}}\right)$ and small enough so that $\hat{\mathrm{B}}\left(a, r_{a}\right)=$ $\varphi_{i_{a}}^{-1}\left(B_{i_{a}} \cap \mathrm{~B}\left(\varphi_{i_{a}}(a), r_{a}\right)\right) \subset\left\{x \in D: d(x, A) \leq \frac{1}{j+1}\right\}$. Choose a finite number of sets $\hat{\mathrm{B}}\left(a_{m}^{j+1}, r_{a_{m}^{j+1}}\right), m=1, \ldots, s_{j+1}$, with $a_{m}^{j+1} \in A, m=1, \ldots, s_{j+1}$, and such that $A \subset \bigcup_{m=1}^{s_{j+1}} \hat{\mathrm{~B}}\left(a_{m}^{j+1}, r_{a_{m}^{j+1}}\right)$, and define $A_{j+1}:=\bigcup_{m=1}^{s_{j+1}} \overline{\hat{\mathrm{~B}}\left(a_{m}^{j+1}, r_{a_{m}^{j+1}}\right)}$.

Clearly, $\left(A_{j}\right)_{j \in \mathrm{~N}}$ is a decreasing sequence of compact sets being finite unions of closed "balls" with $\bigcap_{j=1}^{\infty} A_{j}=A$.

In the subcase where $D$ is a manifold the above construction is carried out with $B_{i}=V_{i}$.

Two cases have to be considered.
Case 1. The case where (2) is satisfied.
Using Corollary 4.5.9 from [13] (which is also true for our context and our "balls", with a proof which goes along the same lines as in [13]: we only need to use the approximation of $D$ by strongly pseudoconvex domains and Theorem 10.4 from [18] instead of Proposition 4.5.3, and pass to $C^{n}$ by charts) we see that $h_{A_{j}, D}=h_{A_{j}, D}^{\star}$ is continuous. Then we have

$$
h_{\left\{h_{A_{j}, D} \leq r\right\}, D}=\max \left\{0, \frac{h_{A_{j}, D}-r}{1-r}\right\} .
$$

Also, $h_{A_{j}, D} \nearrow h_{A, D}$ as $j \nearrow \infty$ (in view of Proposition 2.9). Hence $\left\{h_{A_{j}, D} \leq\right.$ $r\} \searrow\left\{h_{A, D} \leq r\right\}$ as $j \nearrow \infty$. Thus $h_{\left\{h_{A_{j}, D} \leq r\right\}, D} \nearrow h_{\left\{h_{A, D} \leq r\right\}, D}$, from which follows

$$
h_{\left\{h_{A, D} \leq r\right\}, D}=\max \left\{0, \frac{h_{A, D}-r}{1-r}\right\} \leq R .
$$

Hence $h_{\left\{h_{A, D} \leq r\right\}, D}^{\star} \leq R$. Since the set $\left\{h_{A, D} \leq r\right\} \backslash \Delta[r]$ is pluripolar, $h_{\Delta[r], D}^{\star} \leq$ $R$ and, as in Step $5, L \equiv R$.

Case 2. The case where (1) is satisfied and $A$ is additionally holomorphically convex.

Here we do not know if the relative extremal functions of $A_{j}$ 's are continuous. However, we may once again use the approximation argument to shift the situation to the case of Step 5. It is to do as follows:

For any $j \in \mathrm{~N}$ put $U_{j}:=\bigcup_{m=1}^{s_{j}} \hat{\mathrm{~B}}\left(a_{m}^{j}, r_{a_{m}^{j}}\right)$. Observe that the sequence $\left(U_{j}\right)_{j \in \mathrm{~N}}$ of open sets is decreasing and enjoys property that for any open set $U$ containing $A$ there is an index $j(U)$ with $U_{j} \subset U$ for all $j \geq j(U)$.

We use now Theorem 2.13 for $U_{j}$ 's as follows: for $U_{1}$, using the same method as in the proof of Theorem 2.13 (given in [22]), we find a compact and holomorphically convex set $E_{1}$ with continuous relative extremal function and such that $A \subset \operatorname{int} E_{1} \subset E_{1} \subset U_{1}$ (it suffices to consider $\delta+\varepsilon$ with small $\varepsilon$, instead of $\delta$ in the definition of $E$ in the proof in [22]). Suppose we have found sets $E_{1}, \ldots, E_{j}$ for some $j \in \mathrm{~N}$. In this situation we obtain $E_{j+1}$ using the argument given above for $U_{j+1} \cap \operatorname{int} E_{j}$ instead of $U_{1}$. We easily see that the decreasing sequence of sets $\left(E_{j}\right)_{j \in \mathrm{~N}}$ gives an approximation of $A$ from above by holomorphically convex compacta with continuous relative extremal functions. It now suffices to use the same argument as in the end of the Case 1.

## 4. Applications of the main result

In this section we give some applications of our main result. First we need to define the generalized $(N, k)$-crosses in the context of complex manifolds.

Let $D_{j}$ be an $n_{j}$-dimensional complex manifold and let $\emptyset \neq A_{j} \subset D_{j}$ for $j=$ $1, \ldots, N, N \geq 2$. For $k \in\{1, \ldots, N\}$ let $I(N, k):=\left\{\alpha=\left(\alpha_{1}, \ldots, \alpha_{N}\right) \in\right.$ $\left.\{0,1\}^{N}:|\alpha|=k\right\}$, where $|\alpha|:=\alpha_{1}+\cdots+\alpha_{N}$. Put

$$
\mathscr{X}_{\alpha, j}:=\left\{\begin{array}{ll}
D_{j}, & \text { if } \alpha_{j}=1 \\
A_{j}, & \text { if } \alpha_{j}=0
\end{array}, \quad \mathscr{X}_{\alpha}:=\prod_{j=1}^{N} \mathscr{X}_{\alpha, j}\right.
$$

For an $\alpha \in I(N, k)$ such that $\alpha_{r_{1}}=\cdots=\alpha_{r_{k}}=1, \alpha_{i_{1}}=\cdots=\alpha_{i_{N-k}}=0$, where $r_{1}<\cdots<r_{k}$ and $i_{1}<\cdots<i_{N-k}$, put

$$
D_{\alpha}:=\prod_{s=1}^{k} D_{r_{s}}, \quad A_{\alpha}:=\prod_{s=1}^{N-k} A_{i_{s}}
$$

For an $a=\left(a_{1}, \ldots, a_{N}\right) \in \mathscr{X}_{\alpha}, \alpha$ as above, put $a_{\alpha}^{0}:=\left(a_{i_{1}}, \ldots, a_{i_{N-k}}\right) \in A_{\alpha}$. Analogously, define $a_{\alpha}^{1}:=\left(a_{r_{1}}, \ldots, a_{r_{k}}\right) \in D_{\alpha}$. For every $\alpha \in I(N, k)$ and every $a=\left(a_{i_{1}}, \ldots, a_{i_{N-k}}\right) \in A_{\alpha}$ define

$$
\begin{aligned}
\boldsymbol{i}_{a, \alpha} & =\left(\boldsymbol{i}_{a, \alpha, 1}, \ldots, \boldsymbol{i}_{a, \alpha, N}\right): D_{\alpha} \rightarrow \mathscr{X}_{\alpha}, \\
\boldsymbol{i}_{a, \alpha, j}(z) & :=\left\{\begin{array}{ll}
z_{j}, & \text { if } \alpha_{j}=1 \\
a_{j}, & \text { if } \alpha_{j}=0
\end{array}, \quad j=1, \ldots, N, \quad z=\left(z_{r_{1}}, \ldots, z_{r_{k}}\right) \in D_{\alpha}\right.
\end{aligned}
$$

(if $\alpha_{j}=0$, then $j \in\left\{i_{1}, \ldots, i_{N-k}\right\}$ and if $\alpha_{j}=1$, then $j \in\left\{r_{1}, \ldots, r_{k}\right\}$ ). Similarly, for any $\alpha \in I(N, k)$ and any $b=\left(b_{r_{1}}, \ldots, b_{r_{k}}\right) \in D_{\alpha}$ define

$$
\begin{aligned}
\boldsymbol{l}_{b, \alpha} & =\left(\boldsymbol{l}_{b, \alpha, 1}, \ldots, \boldsymbol{l}_{b, \alpha, N}\right): A_{\alpha} \rightarrow \mathscr{X}_{\alpha} \\
\boldsymbol{l}_{b, \alpha, j}(z) & :=\left\{\begin{array}{ll}
z_{j}, & \text { if } \alpha_{j}=0 \\
b_{j}, & \text { if } \alpha_{j}=1
\end{array}, \quad j=1, \ldots, N, \quad z=\left(z_{i_{1}}, \ldots, z_{i_{N-k}}\right) \in A_{\alpha} .\right.
\end{aligned}
$$

Definition 4.1 (cf. [14]). For any $\alpha \in I(N, k)$ let $\Sigma_{\alpha} \subset A_{\alpha}$. We define a generalized $(N, k)$-cross

$$
\mathbf{T}_{N, k}:=\mathbf{T}_{N, k}\left(\left(A_{j}, D_{j}\right)_{j=1}^{N},\left(\Sigma_{\alpha}\right)_{\alpha \in I(N, k)}\right)=\bigcup_{\alpha \in I(N, k)}\left\{a \in \mathscr{X}_{\alpha}: a_{\alpha}^{0} \notin \Sigma_{\alpha}\right\}
$$

and its center

$$
\mathfrak{C}\left(\mathbf{T}_{N, k}\right):=\mathbf{T}_{N, k} \cap\left(A_{1} \times \cdots \times A_{N}\right) .
$$

It is straightforward that

$$
\mathfrak{C}\left(\mathbf{T}_{N, k}\right)=\left(A_{1} \times \cdots \times A_{N}\right) \backslash \bigcap_{\alpha \in I(N, k)}\left\{z \in A_{1} \times \cdots \times A_{N}: z_{\alpha}^{0} \in \Sigma_{\alpha}\right\}
$$

which implies that $\mathfrak{C}\left(\mathbf{T}_{N, k}\right)$ is non-pluripolar provided that $A_{1} \times \cdots \times A_{N}$ is nonpluripolar and at least one of the $\Sigma_{\alpha}$ 's is pluripolar (cf. [12], Proposition 2.3.31). Note that if we take $\Sigma_{\alpha}=\emptyset$ for every $\alpha \in I(N, k)$, then in the definition above we get the ( $N, k$ )-cross (see [11])

$$
\mathbf{X}_{N, k}=\mathrm{X}_{N, k}\left(\left(A_{j}, D_{j}\right)_{j=1}^{N}\right):=\mathrm{T}_{N, k}\left(\left(A_{j}, D_{j}\right)_{j=1}^{N},(\emptyset)_{\alpha \in I(N, k)}\right)
$$

Definition 4.2 ([11]). For an ( $N, k$ )-cross define its envelope by

$$
\begin{aligned}
\hat{\mathbf{X}}_{N, k} & =\hat{\mathrm{X}}_{N, k}\left(\left(A_{j}, D_{j}\right)_{j=1}^{N}\right) \\
& :=\left\{\left(z_{1}, \ldots, z_{N}\right) \in D_{1} \times \ldots \times D_{N}: \sum_{j=1}^{N} h_{A_{j}, D_{j}}^{\star}\left(z_{j}\right)<k\right\}
\end{aligned}
$$

Note the obvious inclusion $\hat{\mathbf{X}}_{N, k-1} \subset \hat{\mathbf{X}}_{N, k}$.
As it was already mentioned, using Theorem 1.1 we may derive a formula for the relatively extremal function of the envelope of $(N, k-1)$-cross with respect to the envelope of $(N, k)$-cross, which will play a fundamental role in the proof of Theorem 4.6.

Theorem 4.3. Let $D_{j}$ be a Stein manifold and let $A_{j} \subset D_{j}$ be locally pluriregular, $j=1, \ldots, N$. Then
$h_{\hat{\mathbf{x}}_{N, k-1}, \hat{\mathbf{X}}_{N, k}}^{\star}(z)=\max \left\{0, \sum_{j=1}^{N} h_{A_{j}, D_{j}}^{\star}\left(z_{j}\right)-k+1\right\}, \quad z=\left(z_{1}, \ldots, z_{N}\right) \in \hat{\mathbf{X}}_{N, k}$.
Proof. We carry out this proof exactly the same as in [11], bearing in mind that the product property for relatively extremal function is true also for domains in Stein manifolds (see [6]).

In fact, using [5], we easily see that Theorem 4.3 holds true also in the situation where the $D_{j}$ 's are irreducible, locally irreducible, weakly parabolic Stein spaces.

Definition 4.4. We say that a function $f: \mathbf{T}_{N, k} \rightarrow \mathrm{C}$ is separately holomorphic on $\mathbf{T}_{N, k}$ if for every $\alpha \in I(N, k)$ and for every $a \in A_{\alpha} \backslash \Sigma_{\alpha}$ the function

$$
D_{\alpha} \ni z \mapsto f\left(\boldsymbol{i}_{a, \alpha}(z)\right)
$$

is holomorphic. In this case we write $f \in \mathscr{O}_{s}\left(\mathbf{T}_{N, k}\right)$.
We denote by $\mathscr{O}_{s}^{c}\left(\mathbf{T}_{N, k}\right)$ the space of all $f \in \mathscr{O}_{s}\left(\mathbf{T}_{N, k}\right)$ such that for any $\alpha \in I(N, k)$ and for every $b \in D_{\alpha}$ the function

$$
A_{\alpha} \backslash \Sigma_{\alpha} \ni z \mapsto f\left(l_{b, \alpha}(z)\right)
$$

is continuous.

Theorem 4.5 (cf. [12], Theorem 7.1.4). Let $D_{j}$ be a Stein manifold, let $A_{j} \subset D_{j}$ be locally pluriregular, $j=1, \ldots, N$. Let $\Sigma_{\alpha} \subset A_{\alpha}$ be pluripolar, $\alpha \in I(N, 1) . \operatorname{Put} \mathbf{X}_{N, 1}:=\mathrm{X}_{N, 1}\left(\left(A_{j}, D_{j}\right)_{j=1}^{N}\right), \mathbf{T}_{N, 1}:=\mathrm{T}_{N, 1}\left(\left(A_{j}, D_{j}, \Sigma_{j}\right)_{j=1}^{N}\right)$. Let $f \in \mathcal{O}_{s}^{c}\left(\mathbf{X}_{N, 1}\right)$. Then there exists a uniquely determined $\hat{f} \in \mathcal{O}\left(\hat{\mathbf{X}}_{N, 1}\right)$ such that $\hat{f}=f$ on $\mathbf{T}_{N, 1}$ and $\hat{f}\left(\hat{\mathbf{X}}_{N, 1}\right) \subset f\left(\mathbf{T}_{N, 1}\right)$.

Proof. The proof may be rewritten almost verbatim from [12].
Theorem 4.6. Let $D_{j}$ be a union of an increasing sequence of Stein manifolds and let $A_{j} \subset D_{j}$ be locally pluriregular, $j=1, \ldots, N$. Take $\Sigma_{\alpha} \subset A_{\alpha}$ pluripolar, $\alpha \in I(N, k)$ and put $\mathbf{T}_{N, k}:=\mathrm{T}_{N, k}\left(\left(A_{j}, D_{j}\right)_{j=1}^{N},\left(\Sigma_{\alpha}\right)_{\alpha \in I(N, k)}\right)$, $\mathbf{X}_{N, k}:=\mathbf{X}_{N, k}\left(\left(A_{j}, D_{j}\right)_{j=1}^{N}\right)$. Then any function $f \in \mathscr{F}:=\mathscr{O}_{s}^{c}\left(\mathbf{T}_{N, k}\right)$ admits a holomorphic extension $\hat{f} \in \mathcal{O}\left(\hat{\mathbf{X}}_{N, k}\right)$ such that $\hat{f}=f$ on $\mathbf{T}_{N, k}$ and $\hat{f}\left(\hat{\mathbf{X}}_{N, k}\right) \subset f\left(\mathbf{T}_{N, k}\right)$.

Proof. The inclusion $\hat{f}\left(\hat{\mathbf{X}}_{N, k}\right) \subset f\left(\mathbf{T}_{N, k}\right)$ for $f \in \mathscr{F}$ is to obtain in a standard way (cf. [12], Lemma 2.1.14; observe it is also true in our context).

Observe that without loss of generality we may assume that each $D_{j}$ is a Stein manifold. Furthermore, for each $D_{j}$ we may find an exhausting sequence of strongly pseudoconvex relatively compact open sets with smooth boundaries (by considering sublevel sets of a smooth strictly plurisubharmonic exhaustion function for each $D_{j}$ ). Thus, it is enough to prove the theorem with additional assumptions that each $D_{j}$ is strongly pseudoconvex relatively compact open subset (with smooth boundary) of some Stein manifold $\tilde{D}_{j}$ and $A_{j} \subset \subset D_{j}$.

We apply induction over $N$. There is nothing to prove in the case $N=k$. Moreover, the case $k=1$ is solved by Theorem 4.5. Thus, the conclusion holds true for $N=2$. Suppose it holds true for $N-1 \geq 2$. Now, we apply induction over $k$. For $k=1$, as mentioned, the result is known. Suppose that the conclusion is true for $k-1$ with $2 \leq k \leq N-1$.

Fix an $f \in \mathscr{F}$. Define

$$
Q:=Q_{N}=\left\{z_{N} \in A_{N}: \exists \alpha \in I_{0}(N, k):\left(\Sigma_{\alpha}\right)_{\left(\cdot, z_{N}\right)} \notin \mathscr{P} \mathscr{L} \mathscr{P}\right\}
$$

where $I_{0}(N, k):=I(N, k) \cap\left\{\alpha: \alpha_{N}=0\right\}$. Then $Q \in \mathscr{P} \mathscr{L} \mathscr{P}$ (cf. [12], Proposition 2.3.31). For a $z_{N} \in A_{N} \backslash Q$ put

$$
\mathbf{T}_{N-1, k}\left(z_{N}\right):=\mathrm{T}_{N-1, k}\left(\left(A_{j}, D_{j}\right)_{j=1}^{N-1},\left(\left(\Sigma_{(\beta, 0)}\right)_{\left(\cdot, z_{N}\right)}\right)_{\beta \in I(N-1, k)}\right)
$$

Consider also the generalized ( $N-1, k-1$ )-cross

$$
\mathbf{T}_{N-1, k-1}:=\mathbf{T}_{N-1, k-1}\left(\left(A_{j}, D_{j}\right)_{j=1}^{N-1},\left(\Sigma_{(\beta, 1)}\right)_{\beta \in I(N-1, k-1)}\right) .
$$

It can be easily seen that for a fixed $z_{N} \in A_{N} \backslash Q$ we have

$$
\left(\mathbf{T}_{N, k}\right)_{\left(\cdot, z_{N}\right)}=\mathbf{T}_{N-1, k}\left(z_{N}\right) \cup \mathbf{T}_{N-1, k-1},
$$

where $\left(\mathbf{T}_{N, k}\right)_{\left(\cdot, z_{N}\right)}$ is the fiber of the set $\mathbf{T}_{N, k}$ over $z_{N}$. Define

$$
\mathbf{Y}_{N-1, k}:=\mathrm{X}_{N-1, k}\left(\left(A_{j}, D_{j}\right)_{j=1}^{N-1}\right), \quad \mathbf{Y}_{N-1, k-1}:=\mathrm{X}_{N-1, k-1}\left(\left(A_{j}, D_{j}\right)_{j=1}^{N-1}\right)
$$

For any $z_{N} \in A_{N} \backslash Q$ we have $f\left(\cdot, z_{N}\right) \in \mathscr{O}_{s}^{c}\left(\mathbf{T}_{N-1, k}\left(z_{N}\right)\right)$ and, moreover, for any $z_{N} \in D_{N}$ we have $f\left(\cdot, z_{N}\right) \in \mathscr{O}_{s}^{c}\left(\mathbf{T}_{N-1, k-1}\right)$. Then, by inductive assumption, for any $z_{N} \in A_{N} \backslash Q$ there exists an $\hat{f}_{z_{N}} \in \mathcal{O}\left(\hat{\mathbf{Y}}_{N-1, k}\right)$ such that $\hat{f}_{z_{N}}=f\left(\cdot, z_{N}\right)$ on $\mathbf{T}_{N-1, k}\left(z_{N}\right)$. Analogously, for any $z_{N} \in D_{N}$ there exists a $\hat{g}_{z_{N}} \in \mathscr{O}\left(\hat{\mathbf{Y}}_{N-1, k-1}\right)$ such that $\hat{g}_{z_{N}}=f\left(\cdot, z_{N}\right)$ on $\mathbf{T}_{N-1, k-1}$.

Define a 2-fold classical cross (cf. [10])

$$
\mathbf{Z}:=\mathrm{X}_{2,1}\left(\left(B_{j}, E_{j}\right)_{j=1}^{2}\right)
$$

where $B_{1}=\hat{\mathbf{Y}}_{N-1, k-1}, B_{2}=A_{N} \backslash Q, E_{1}=\hat{\mathbf{Y}}_{N-1, k}, E_{2}=D_{N}$. Clearly

$$
\mathbf{Z}=\left(\hat{\mathbf{Y}}_{N-1, k-1} \times D_{N}\right) \cup\left(\hat{\mathbf{Y}}_{N-1, k} \times\left(A_{N} \backslash Q\right)\right)
$$

Applying Theorem 4.3 and pluripolarity of $Q$ we get $\hat{\mathbf{Z}}=\hat{\mathbf{X}}_{N, k}$.
Let $F: \mathbf{Z} \rightarrow \mathbf{C}$ be given by the formula

$$
F\left(z^{\prime}, z_{N}\right):= \begin{cases}\hat{f}_{z_{N}}\left(z^{\prime}\right), & \text { if }\left(z^{\prime}, z_{N}\right) \in \hat{\mathbf{Y}}_{N-1, k} \times\left(A_{N} \backslash Q\right), \\ \hat{g}_{z_{N}}\left(z^{\prime}\right), & \text { if }\left(z^{\prime}, z_{N}\right) \in \hat{\mathbf{Y}}_{N-1, k-1} \times D_{N}\end{cases}
$$

First, observe that $F$ is well-defined. Indeed, we only have to check that for any $z_{N} \in A_{N} \backslash Q$ we have equality $\hat{f}_{z_{N}}=\hat{g}_{z_{N}}$ on $\hat{\mathbf{Y}}_{N-1, k-1}$. In fact, since both $\hat{f}_{z_{N}}$ and $\hat{g}_{z_{N}}$ are extensions of $f\left(\cdot, z_{N}\right)$, we only need to prove existence of some non-pluripolar set $B \subset \mathbf{T}_{N-1, k}\left(z_{N}\right) \cap \mathbf{T}_{N-1, k-1}$ and use the identity principle. Observe that the set

$$
B:=\mathfrak{C}\left(\mathbf{T}_{N-1, k}\left(z_{N}\right)\right) \cap \mathfrak{C}\left(\mathbf{T}_{N-1, k-1}\right)
$$

is good for our purpose.
Now we prove that $F \in \mathscr{O}_{S}(\mathbf{Z})$. We have to prove that for each $z^{\prime} \in \hat{\mathbf{Y}}_{N-1, k-1}$ the function $D_{N} \in z_{N} \mapsto F\left(z^{\prime}, z_{N}\right)$ is holomorphic (or equivalently, that $\left.F \in \mathscr{O}\left(\hat{\mathbf{Y}}_{N-1, k-1} \times D_{N}\right)\right)$. We already know that $F\left(\cdot, z_{N}\right)$ is holomorphic for every $z_{N} \in D_{N}$. To show that $F \in \mathscr{O}\left(\hat{\mathbf{Y}}_{N-1, k-1} \times D_{N}\right)$ we will use Terada's theorem (or the Cross theorem for manifolds - see [12], Theorem 6.2.2). Put

$$
\begin{aligned}
\mathbf{W}_{N-1, k-1} & :=\mathrm{T}_{N-1, k-1}\left(\left(A_{j}, D_{j}\right)_{j=2}^{N},\left(\Sigma_{(1, \beta)}\right)_{\beta \in I(N-1, k-1)}\right), \\
\mathbf{Z}_{N-1, k-1} & :=\mathbf{X}_{N-1, k-1}\left(\left(A_{j}, D_{j}\right)_{j=2}^{N}\right) .
\end{aligned}
$$

From the inductive assumption, for any $z_{1} \in D_{1}$ there exists an $\hat{h}_{z_{1}} \in$ $\mathscr{O}\left(\hat{\mathbf{Z}}_{N-1, k-1}\right)$ with $\hat{h}_{z_{1}}=f\left(z_{1}, \cdot\right)$ on $\mathbf{W}_{N-1, k-1}$. Thus we get

$$
\begin{aligned}
F\left(z_{1}, \ldots, z_{N}\right) & =f\left(z_{1}, \ldots, z_{N}\right) \\
& =\hat{h}_{z_{1}}\left(z_{2}, \ldots, z_{N}\right)
\end{aligned}
$$

for $\left(z_{1}, \ldots, z_{N}\right) \in\left(\mathbf{T}_{N-1, k-1} \times D_{N}\right) \cap\left(D_{1} \times \mathbf{W}_{N-1, k-1}\right)$. It suffices to show that there exists a non-pluripolar set $C$ such that

$$
C \times D_{N} \subset\left(\mathbf{T}_{N-1, k-1} \times D_{N}\right) \cap\left(D_{1} \times \mathbf{W}_{N-1, k-1}\right)
$$

It is easy to see that the set with the required properties is

$$
C:=\mathfrak{C}\left(\mathbf{T}_{N-1, k-1}\right) \backslash \bigcap_{\alpha \in I(N, k): \alpha_{1}=\alpha_{N}=1}\left\{z \in \prod_{j=1}^{N-1} A_{j}: z_{\alpha}^{0} \in \Sigma_{\alpha}\right\} .
$$

From the Cross theorem for manifolds we get the existence of a function $\hat{f} \in \mathcal{O}(\hat{\mathbf{Z}})$ with $\hat{f}=F$ on $\mathbf{Z}$.

We have to verify that $\hat{f}=f$ on $\mathbf{T}_{N, k}$. Take a point $a \in \mathbf{T}_{N, k}$. The conclusion is obvious if $a \in \mathbf{T}_{N-1, k-1} \times D_{N} \subset \mathbf{Z}$. Suppose, without losing generality, that $a=\left(a_{1}, \ldots, a_{k}, a_{k+1}, \ldots, a_{N}\right) \in D_{1} \times \ldots \times D_{k} \times\left(A_{\alpha} \backslash \Sigma_{\alpha}\right)$, where $\alpha=(\underbrace{1, \ldots, 1}_{k}, \underbrace{0, \ldots, 0}_{N-k})$. Observe that we have

$$
\mathscr{T}:=\bigcup_{z_{N} \in A_{N} \backslash Q} \mathbf{T}_{N-1, k}\left(z_{N}\right) \times\left\{z_{N}\right\} \subset \hat{\mathbf{Y}}_{N-1, k} \times\left(A_{N} \backslash Q\right) \subset \mathbf{Z}
$$

We have also

$$
\mathscr{T} \subset \bigcup_{z_{N} \in A_{N} \backslash Q}\left(\mathbf{T}_{N, k}\right)_{\left(\cdot, z_{N}\right)} \times\left\{z_{N}\right\} \subset \mathbf{T}_{N, k}
$$

Thus, if $b=\left(b^{\prime}, b_{N}\right) \in \mathscr{T}$, then $\hat{f}(b)=F(b)=\hat{f}_{b_{N}}\left(b^{\prime}\right)=f(b)$. Bearing this in mind, we easily see that it suffices to find a sequence

$$
\left(b^{\nu}\right)_{v=1}^{\infty} \subset \mathscr{T} \cap\left\{\left(a_{1}, \ldots, a_{k}\right)\right\} \times\left(A_{\alpha} \backslash \Sigma_{\alpha}\right)
$$

such that $b^{\nu} \rightarrow a$, and then continuity of $f\left(a_{1}, \ldots, a_{k}, \cdot\right)$ will end the proof.
Since $Q$ is pluripolar, there exists a sequence $\left(b_{N}{ }^{\nu}\right)$ convergent to $a_{N}$ such that $\left(b_{N}{ }^{\nu}\right) \subset A_{N} \backslash Q$. Put $P:=\bigcup_{v=1}^{\infty}\left(\Sigma_{\alpha}\right)_{\left(\cdot, b_{N}\right)}{ }^{\nu}$, which is a pluripolar set. This guarantees the existence of a sequence $\left(\left(b_{k+1}{ }^{\nu}, \ldots, b_{N-1}{ }^{\nu}\right)\right) \subset$ $\left(A_{k+1} \times \ldots \times A_{N-1}\right) \backslash P$, convergent to $\left(a_{k+1}, \ldots, a_{N-1}\right)$. Finally we put

$$
\begin{aligned}
& b^{v}:=\left(a_{\alpha}^{1}, b_{k+1}{ }^{v}, \ldots, b_{N-1}{ }^{\nu}\right) \text {. It is obvious that } b^{\nu} \rightarrow a \text { and that for every } \\
& v \in \mathbf{N}, b^{\nu} \in \mathbf{T}_{N-1, k}\left(b_{N}{ }^{v}\right) \times\left\{b_{N}{ }^{v}\right\} \subset \mathscr{T} .
\end{aligned}
$$

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[^0]:    * Project operated within the Foundation for Polish Science IPP Programme "Geometry and Topology in Physical Models" co-financed by the EU European Regional Development Fund, Operational Program Innovative Economy 2007-2013.

    Received 22 May 2012.

