ON NEWTONIAN VECTOR FUNCTIONS

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1. Let the vector

$$V \equiv V(x) \equiv V(x_1, x_2, x_3) \equiv X_1 i + X_2 j + X_3 k$$

be defined in a domain (non-null connected open set) D. If V has continuous partial derivatives of the first order in D, then V is said to be a Newtonian vector [4] provided its curl and divergence both vanish identically in D:

(1)
$$\operatorname{curl} \mathbf{V} \equiv \nabla \times \mathbf{V} \equiv \left(\frac{\partial X_3}{\partial x_2} - \frac{\partial X_2}{\partial x_3}\right) \mathbf{i} + \left(\frac{\partial X_1}{\partial x_3} - \frac{\partial X_3}{\partial x_1}\right) \mathbf{j} + \left(\frac{\partial X_2}{\partial x_1} - \frac{\partial X_1}{\partial x_2}\right) \mathbf{k} = 0$$

(2)
$$\operatorname{div} \mathbf{V} \equiv \nabla \cdot \mathbf{V} \equiv \frac{\partial X_1}{\partial x_1} + \frac{\partial X_2}{\partial x_2} + \frac{\partial X_3}{\partial x_3} = 0.$$

It follows that every Newtonian vector is a harmonic vector.

We can consider (1) and (2) to be analogues of the Cauchy-Riemann equations. The analogy has been carried further by Fulton and Rainich, who obtained a "Cauchy integral formula" [4] and by Beckenbach, who obtained theorems of Morera type [1].

In this note we carry the analogy a little further by obtaining, for Newtonian vectors, analogues of results due to Fédoroff and the present author for analytic functions of one complex variable [3, 6]. We shall prove in detail only a special case of a more general result; the latter will be stated in full at the end of this note.

2. Theorem 1. Let V(x) be continuous in a domain D. Then a necessary and sufficient condition that V(x) be a Newtonian vector is that there exist a fixed null sequence $\{r_k\}$ of positive numbers with the property that

(3)
$$\lim_{k\to\infty} \frac{1}{r_k^5} \iiint_{|x-x_k| \le r_k} (x-x_k) \cdot V(x) \, dv(x) = 0,$$

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(4)
$$\lim_{k\to\infty}\frac{1}{r_k^5}\int\limits_{|x-x_k|\leq r_k}(x-x_k)\times V(x)\ dv(x)=0$$

both hold for every sequence $\{x_k\}$ in D that converges to a point of D.

NECESSITY. If V(x) is a Newtonian vector, then, as remarked above, V(x) has harmonic components. Hence if we expand each component of V(x) in a series of spherical harmonics, say about the point x_0 , and if we make use of the orthogonality relations that exist among these harmonics, then we obtain the well-known relations

(5)
$$\int \int \int \int \int \int (x-x_0) \cdot V(x) \ dv(x) = \frac{4\pi}{15} r_k^5 \nabla \cdot V(x_0) ,$$

(6)
$$\int \int \int \int \int (x-x_0) \times V(x) dv(x) = \frac{4\pi}{15} r_k^5 \nabla \times V(x_0) ,$$

which hold for all sufficiently small r. Now (3) and (4) are trivial consequences of (1), (2), (5) and (6), for any null sequence $\{r_k\}$.

SUFFICIENCY. Now let $\{r_k\}$ be a fixed null sequence of positive numbers such that (3) and (4) hold for all sequences $\{x_k\}$ of points of D that converge to a point of D. The functions

(7)
$$f_k(y) \equiv \frac{1}{r_k^5} \iiint_{|x| = 1} (x - y) \cdot V(x) \, dv(x) ,$$

(8)
$$W_k(y) \equiv \frac{1}{r_k^5} \int_{|x-y| \le r_k} (x-y) \times V(x) \, dv(x)$$

are continuous on a certain subset D_k of D. Moreover, we can show that $\lim_{k\to\infty} f_k(y) = 0$ and $\lim_{k\to\infty} W_k(y) = 0$ uniformly on compact subsets of D. For, if the convergence were not uniform on say the compact set K in D, then there would exist a positive real number δ , and sequences $\{y_k'\}, \{y_k''\}$ of points of K such that $|f_k(y_k')| = \max_{y \in K} |f_k(y)|$ and $|W_k(y_k'')| = \max_{y \in K} |W_k(y)|$ and such that

(9)
$$\liminf_{k \to \infty} |f_k(y_k')| \ge \delta > 0, \qquad \liminf_{k \to \infty} |W_k(y_k'')| \ge \delta > 0$$

both hold. Since K is compact, we may assume that the sequences $\{y_k'\}$, $\{y_k''\}$ converge to points of K, and hence of D. But (9) contradicts (3) and (4). Hence the limits (3) and (4) are uniform limits for x_k on

compact subsets of D. We can replace those equations by

(10)
$$\lim_{k\to\infty} f_k(y) = 0, \quad \lim_{k\to\infty} \mathbf{W}_k(y) = \mathbf{0},$$

which must hold uniformly on compact subsets of D.

We now assume that V(x) has continuous partial derivatives of the first order in D. If we use the finite Taylor expansion

(11)
$$V(x) = V(y) + (x_1 - y_1) \frac{\partial V}{\partial x_1} + (x_2 - y_2) \frac{\partial V}{\partial x_2} + (x_3 - y_3) \frac{\partial V}{\partial x_3} + o(|x - y|)$$

in (7) and (8), then we obtain

$$f_k(y) = \frac{4\pi}{15} \nabla \cdot V(y) + o(1) ,$$

$$\mathbf{W}_k(y) = \frac{4\pi}{15} \nabla \times V(y) + o(1) .$$

From (10) and (12) we obtain (1) and (2).

Suppose now that V(x) is given to be only continuous in D. Then the mean-value functions [2]

$$V^{(\varrho)}(x) \equiv rac{3}{4\pi arrho^2} \iint\limits_{|y-x| \le arrho} V(y) \; dv(y)$$

have continuous partial derivatives of the first order in an open subset D_{ϱ} of D; moreover, it follows from (10) that $V^{(\varrho)}(x)$ satisfies (3) and (4) uniformly on compact subsets of D_{ϱ} . Hence by the preceding argument, it follows that $V^{\varrho}(x)$ is a (harmonic) Newtonian vector in D_{ϱ} . But $V^{(\varrho)}(x) \rightrightarrows V(x)$ on compact subsets of D, as $\varrho \to 0$, so it follows that V(x) must satisfy the equations (1) and (2) in D. This completes the proof.

3. If we examine the proof of Theorem 1, we see that a key to the proof is the pair of relations (5) and (6); essential use is made of the fact that the ellipsoid of inertia of the sphere is again a sphere. This last remark leads to a further generalization of Fédoroff's result, as follows.

Let $\{\Gamma_n\}$ denote a sequence of volumes homeomorphic to |x| < 1 and let δ_n and $|\Gamma_n|$ denote the diameter and volume of Γ_n . We say that $\{\Gamma_n\}$ is a null sequence of volumes if and only if for each $\varepsilon > 0$ there exists $m(\varepsilon)$ such that each Γ_n lies in $|x| < \varepsilon$ for all $n > m(\varepsilon)$. We also say that the sequence $\{\Gamma_n\}$ has the property Q if and only if there is a positive constant a such that the following relations hold for all Γ_n :

$$\iiint_{\Gamma_n} x_k \, dv(x) = \iiint_{\Gamma_n} x_k x_m \, dv(x) = 0, \quad k \neq m, \quad k, m = 1, 2, 3,$$

$$\frac{1}{a} \delta_{n}^{2} |\varGamma_{n}| \, \leqq \, \iiint_{\varGamma_{n}} x_{1}^{2} \, dv(x) \, = \, \iiint_{\varGamma_{n}} x_{2}^{2} \, dv(x) \, = \, \iiint_{\varGamma_{n}} x_{3}^{2} \, dv(x) \, \leqq \, a \, \delta_{n}^{2} |\varGamma_{n}| \, \, .$$

If $\Gamma_n(x) \equiv [x+y \mid y \in \Gamma_n]$ denotes a translate of Γ_n , then we have the following result.

THEOREM 2. Let V(x) be continuous in a domain D. Then a necessary and sufficient condition that V(x) be a Newtonian vector is that there exist a null sequence of volumes, with property Q, such that

$$\lim_{n\to\infty}\frac{1}{\delta_n^2|\Gamma_n|}\int_{\Gamma_n(x_n)}(x-x_n)\cdot V(x)\,dv(x)=0,$$

$$\lim_{n\to\infty}\frac{1}{\delta_n^2|\Gamma_n|}\iiint_{\Gamma_n(x_n)}(x-x_n)\times V(x)\ dv(x)=0$$

hold for each sequence $\{x_n\}$ converging to a point in D.

PROOF. A proof can be given that parallels the proof given above for Theorem 1. We omit the proof.

4. It is clear that the preceding results have analogues in n dimensions, $n \ge 2$. The author has given detailed proofs in [7] for the case n = 2.

The basic idea, that of establishing the uniform limit (10) under the given hypothesis, is due to Müller [5].

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